

# Optical Testing of Mirrors for Giant Telescopes

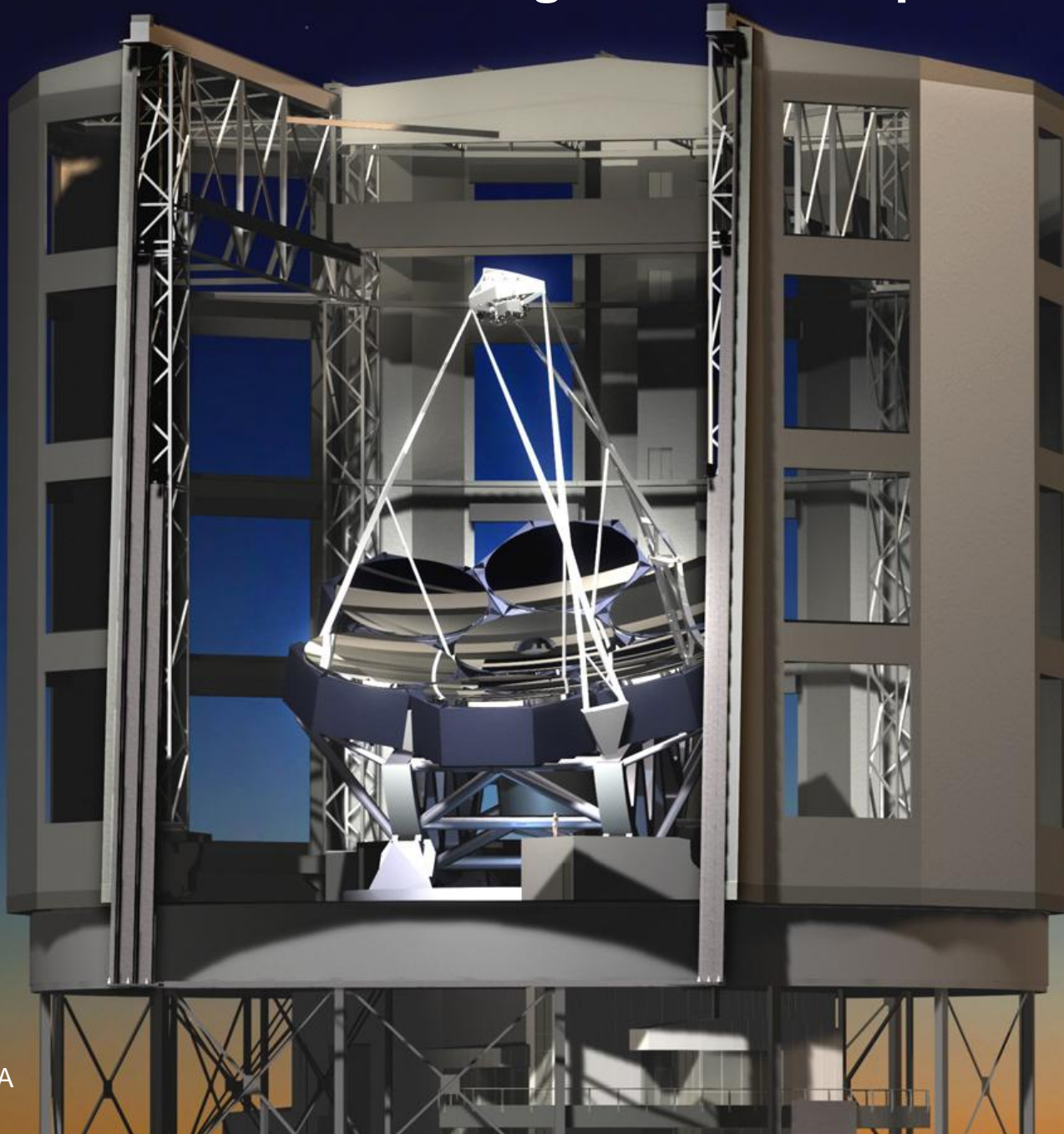
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Steward Observatory  
University of Arizona

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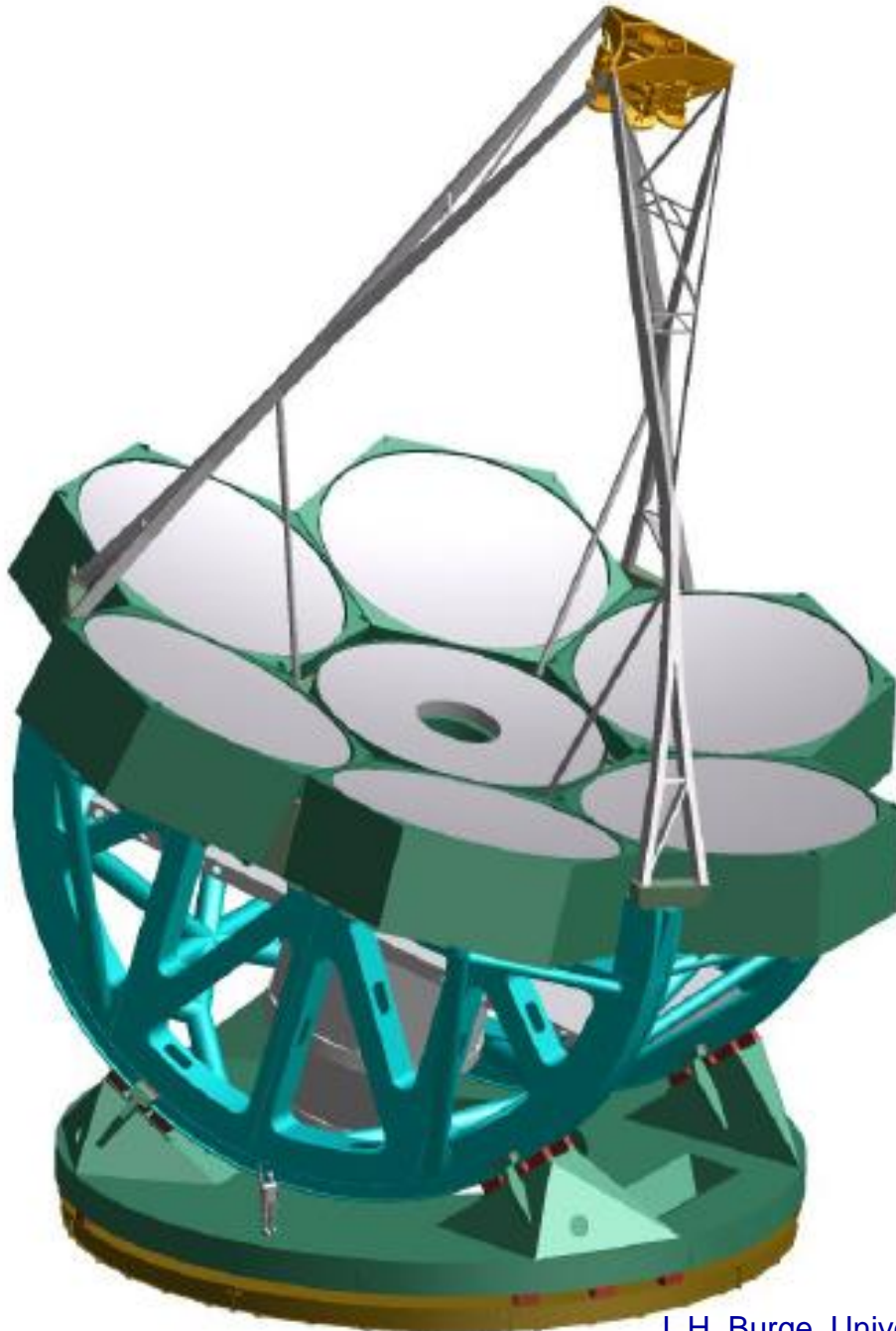
- Introduce giant astronomical telescopes planning to be built in the next decade
- Summarize challenges of testing the mirrors for these telescopes
- Present technologies and capabilities developed at the University of Arizona that enable measurements of the mirrors

# The Giant Magellan Telescope



Site in Chile  
2018 first light  
Consortium with UA

# GMT Design



36 meters high, 25.3 meters across

25-m Primary mirror (f/0.7)

3.2-m segmented secondary mirror  
 corrects for PM position errors  
 deformable mirror for adaptive optics

Alt-Az structure

~1000 tons moving mass

21.3 m azimuth disk

21 m elevation C-ring

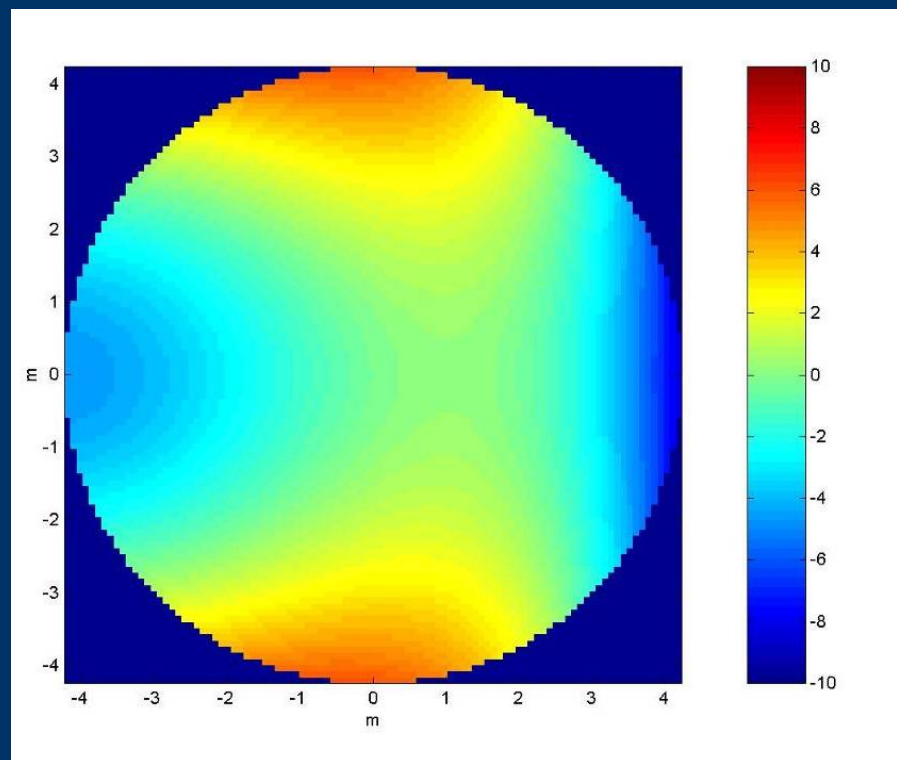
Steel + CFRP secondary support

Instruments mount below primary at  
 the Gregorian focus

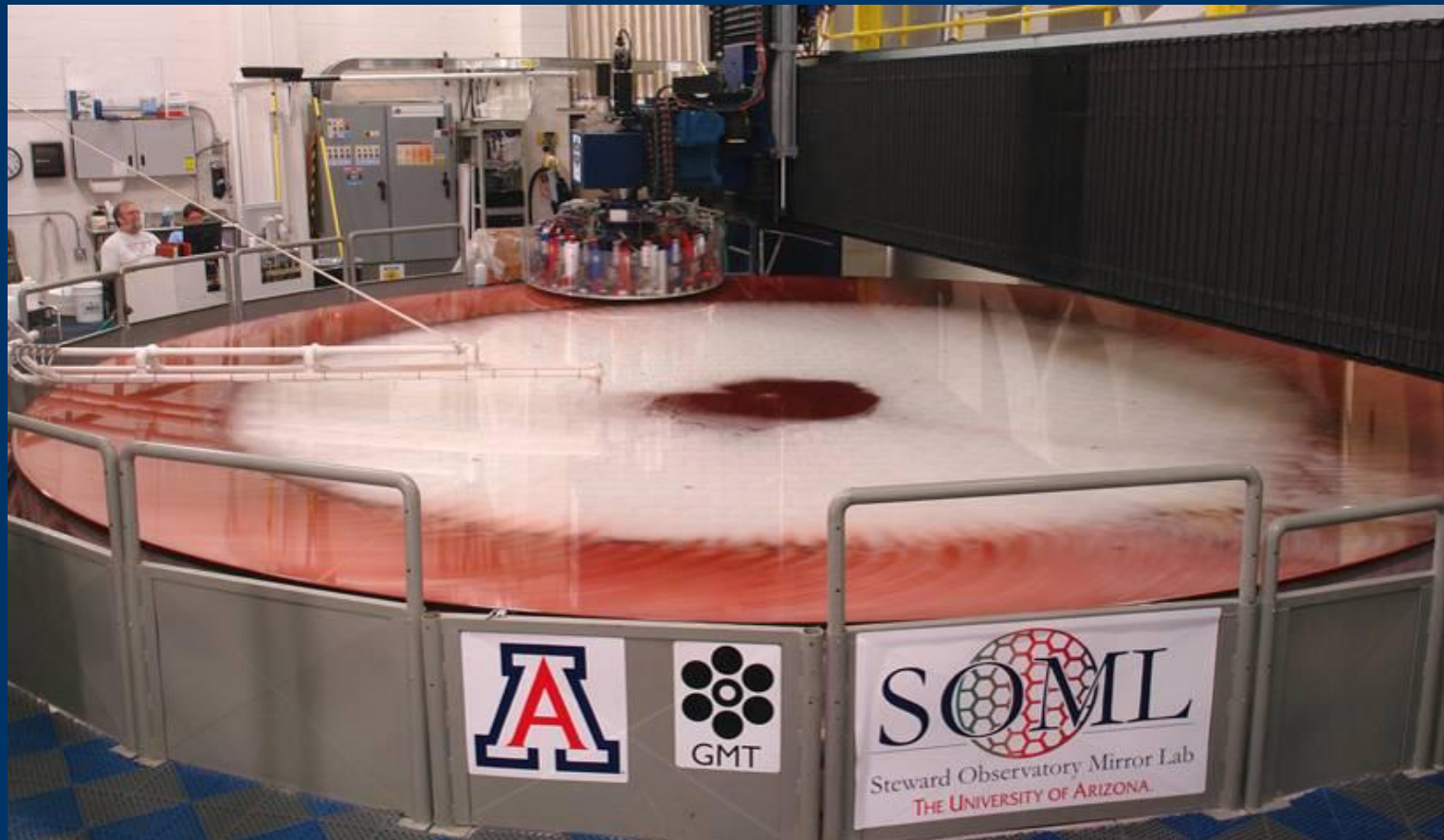
## GMT Primary mirror segments

- Off-axis asphere with ~15 mm aspheric departure
- Segments must match in radius to work together correctly
- For 25-m diameter parent, 36 m ROC is needed

**14.5 mm departure from best fit sphere**



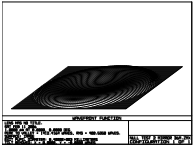
- Aspheric polishing with stressed lap
- Shaping relies on feedback from surface measurement



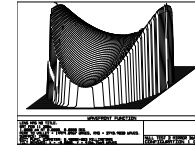
# Optical testing of GMT segments

## Heritage (LBT)

~1.4 mm aspheric departure



~14.5 mm aspheric departure

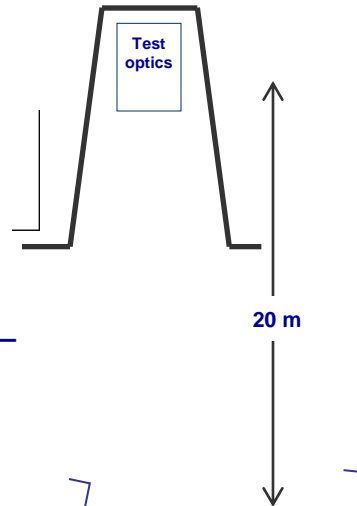


Test wavefront defined  
to match aspheric  
shape  
of mirror

**Axisymmetric**

**Test optics at ~20 meters**

Light from optical test is only 200 mm diameter near the test optics – allows direct measurement of test system

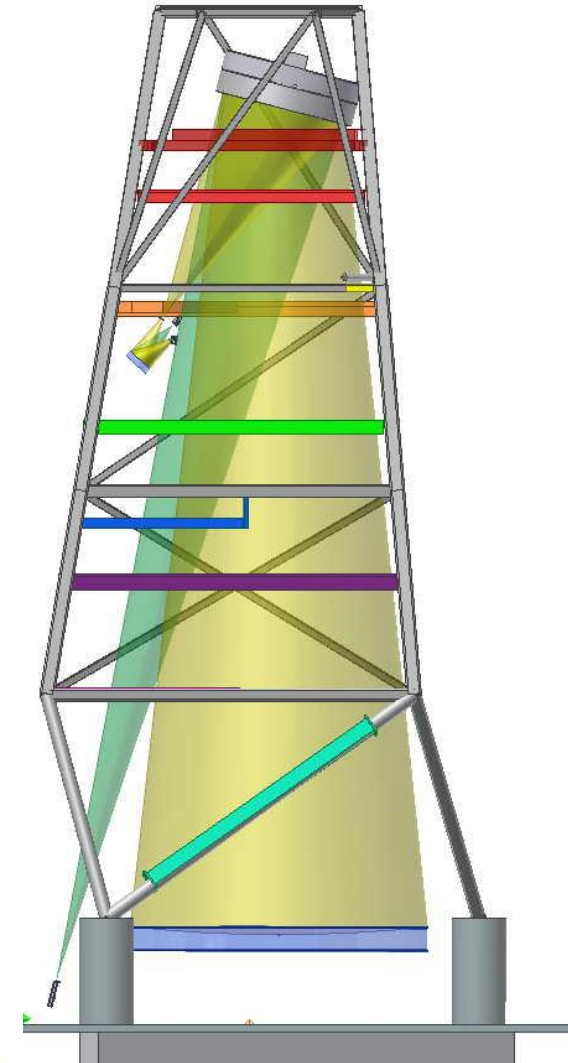
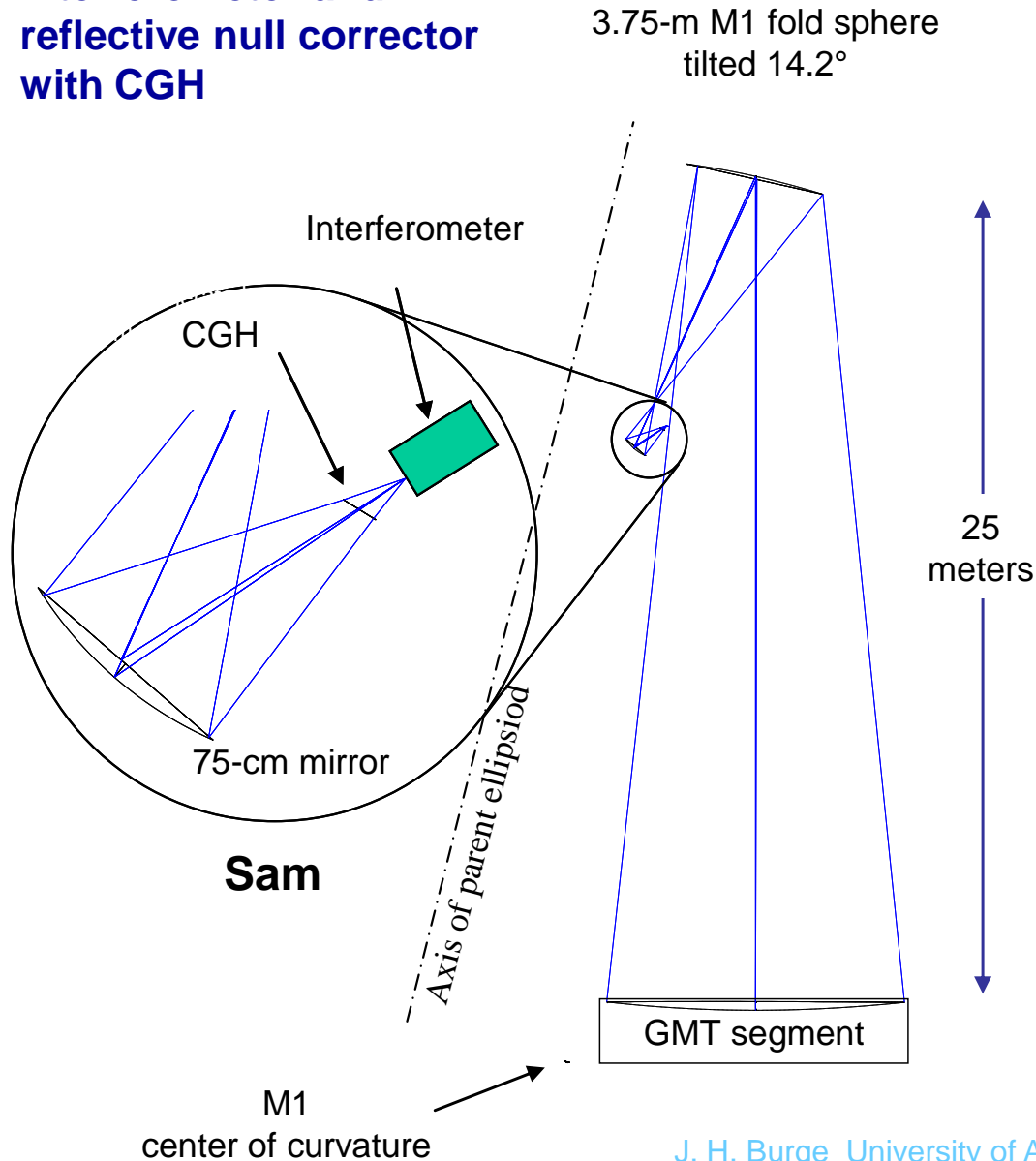


**No Axisymmetry**

Light path defined by GMT is much larger  
(~3.5 meters across at the top of our tower)

# Interferometric surface measurements

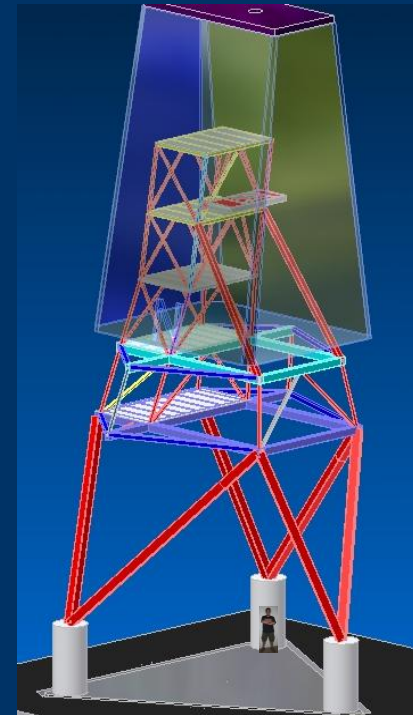
**interferometer and reflective null corrector with CGH**



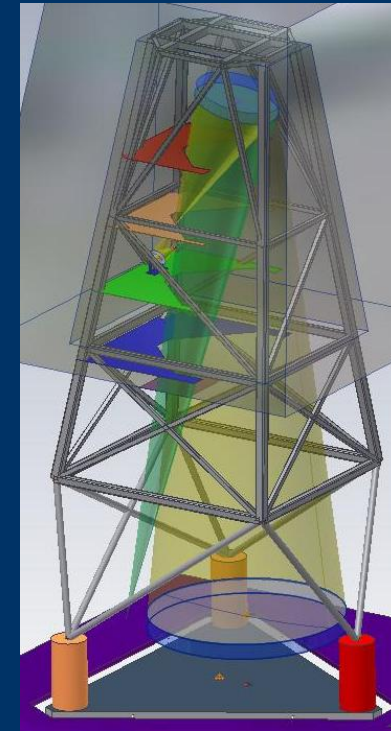




Original tower



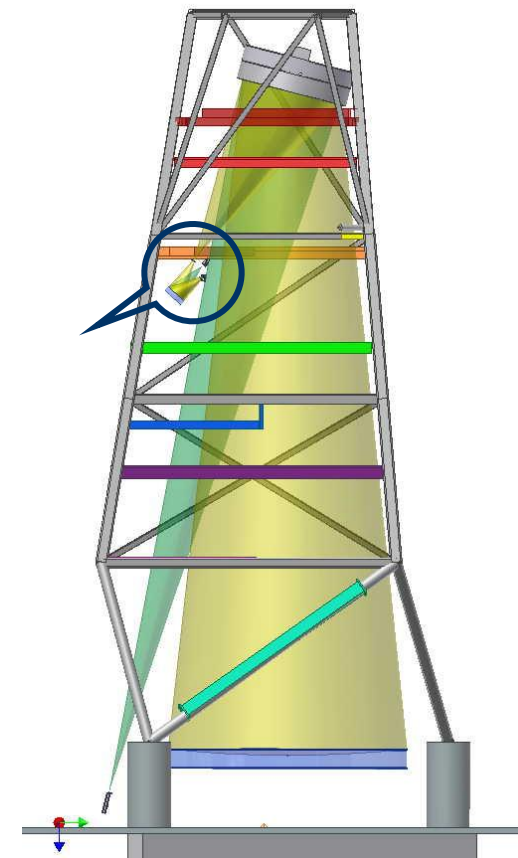
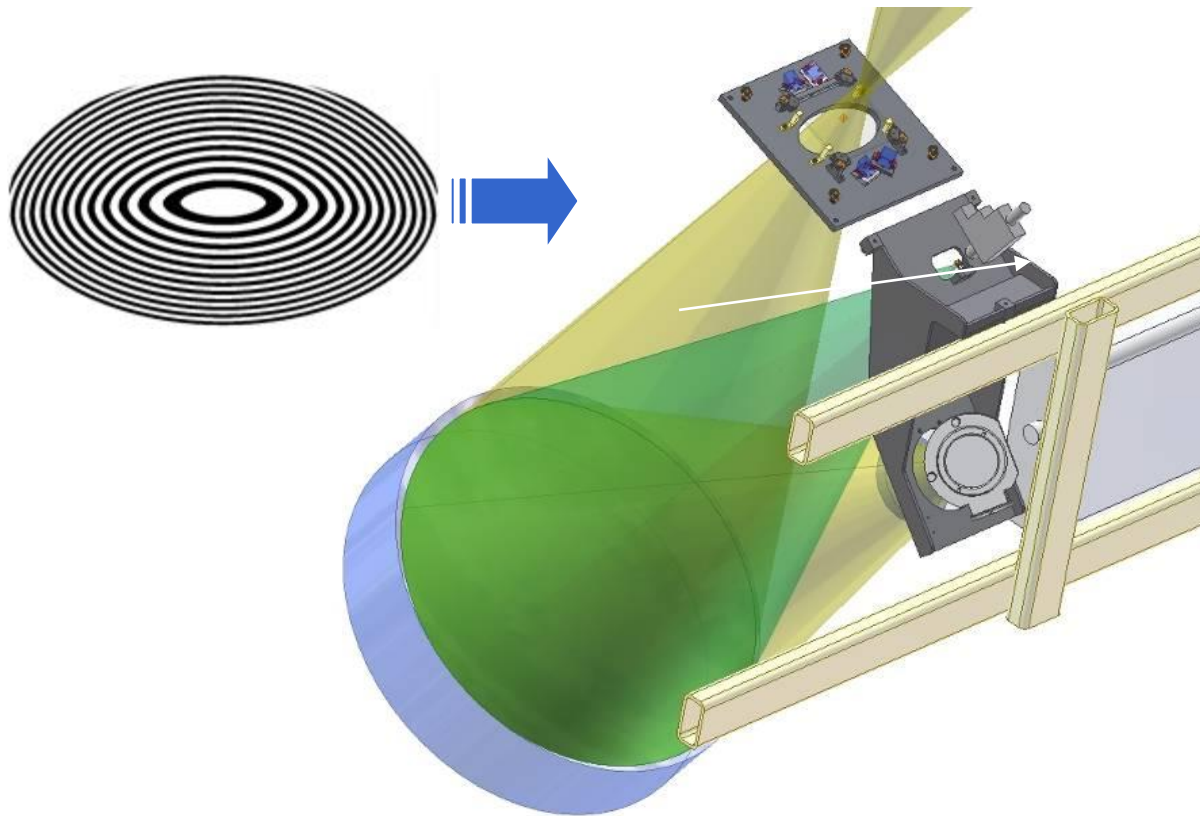
New tower



## New tower

28 meters tall, 80 tons of steel  
floated on 400 ton concrete pad  
accommodates other UA projects (LBT, LSST)  
lowest resonance of 4.8 Hz with 9 ton 3.75-m fold sphere + cell

- CGH inserted into light coming from Sam for alignment test
- Reflection back through system is used to verify wavefront
- CGH mounted on invar plate with other references for M1 alignment



- Reference hologram is aligned to Sam. Then it is used to represent Sam.
- Laser tracker used to measure locations of Sam, fold sphere, GMT
- Fold sphere and GMT actively positioned to ~100  $\mu\text{m}$

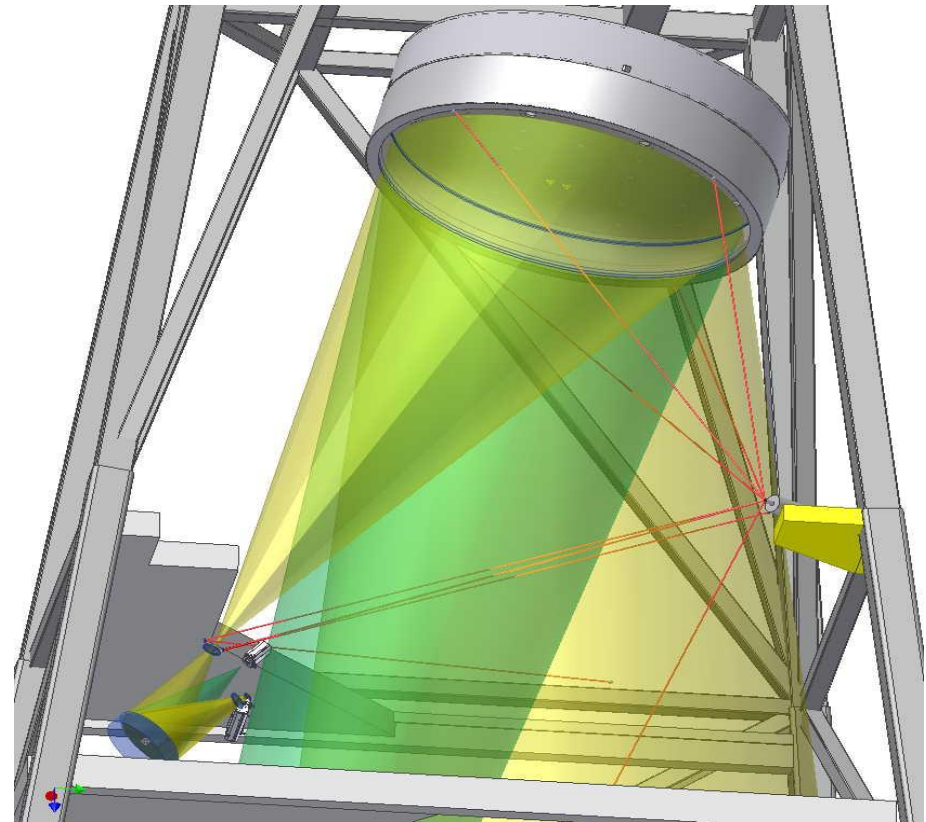
Laser tracker



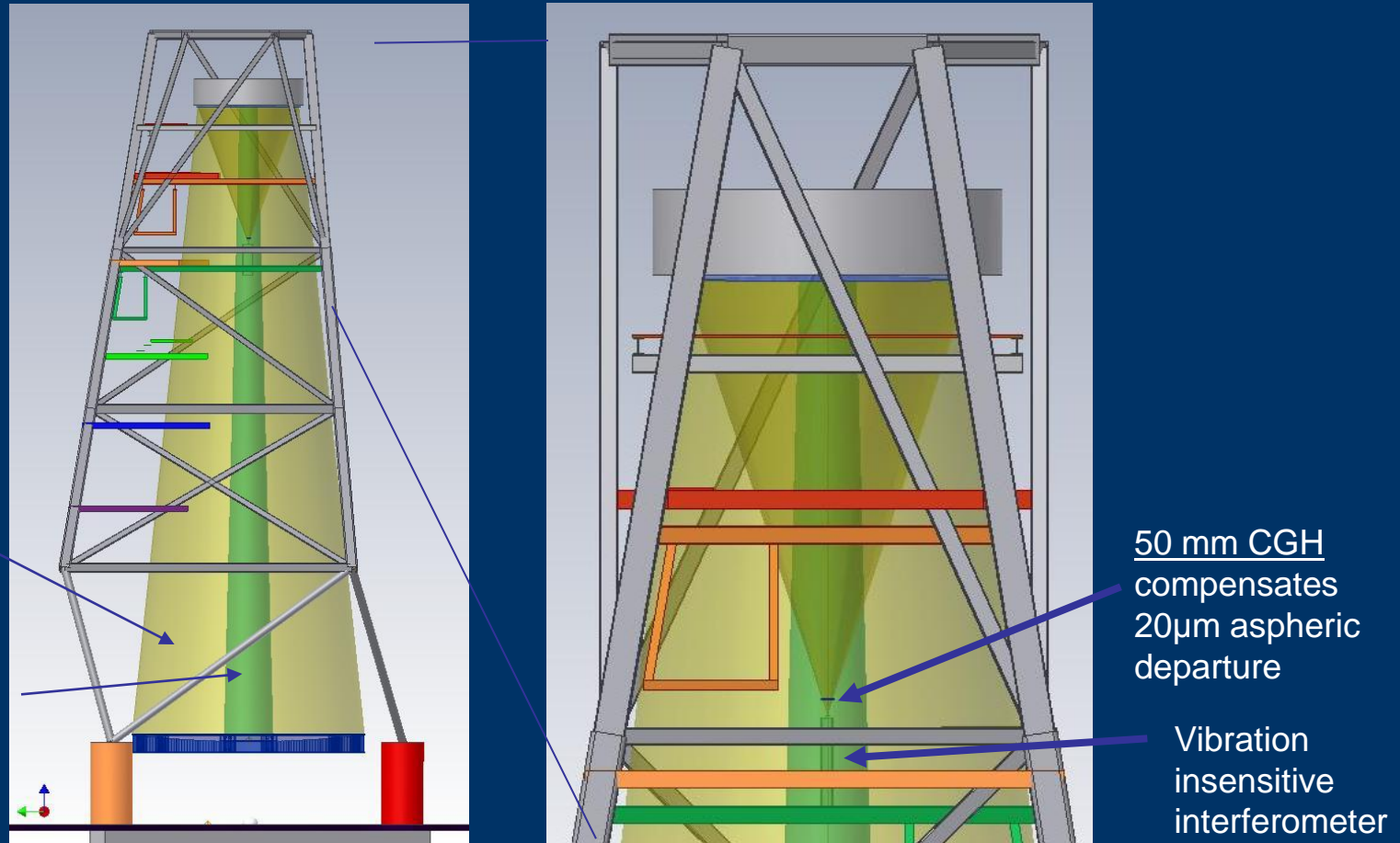
Sphere Mounted Retroreflector



Measures  $\rho$ ,  $\theta$ ,  $\phi$  to determine position to ~25  $\mu\text{m}$

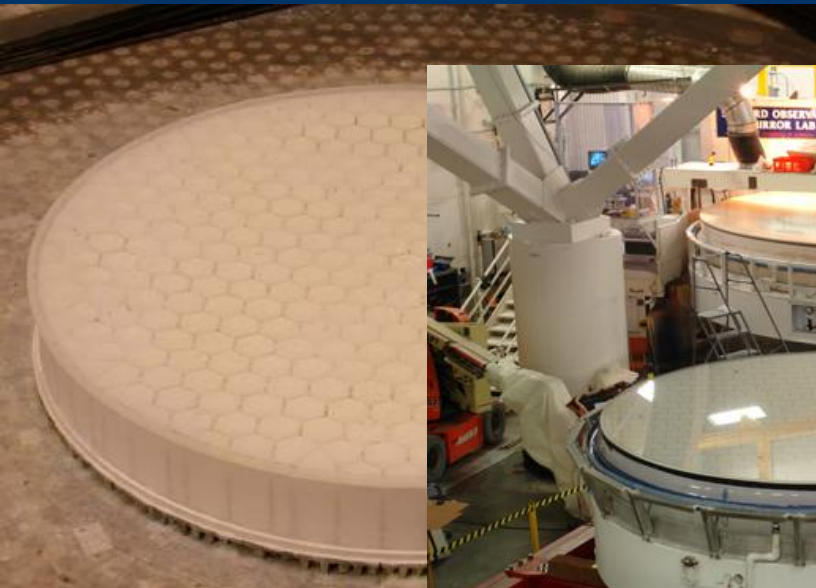


## Tilt the fold sphere to nadir



# 3.75 m fold sphere

- UA produced mirror, mounted at the top of the tower
- Shape is actively controlled based on surface measurements from the center of curvature



Cast in the Mirror Lab spinning oven



Polished, measured at the Mirror Lab



Coated at Kitt Peak

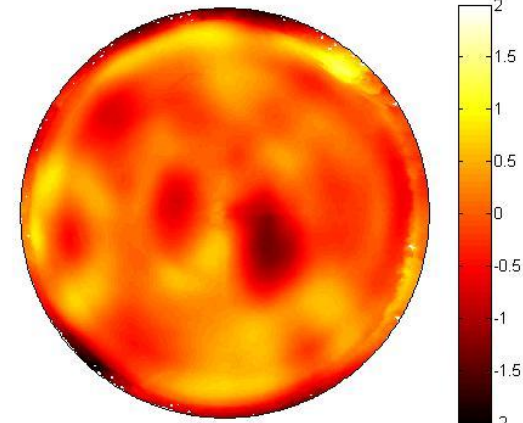
# Operational test system



100430 GMT1 plus0h morphed



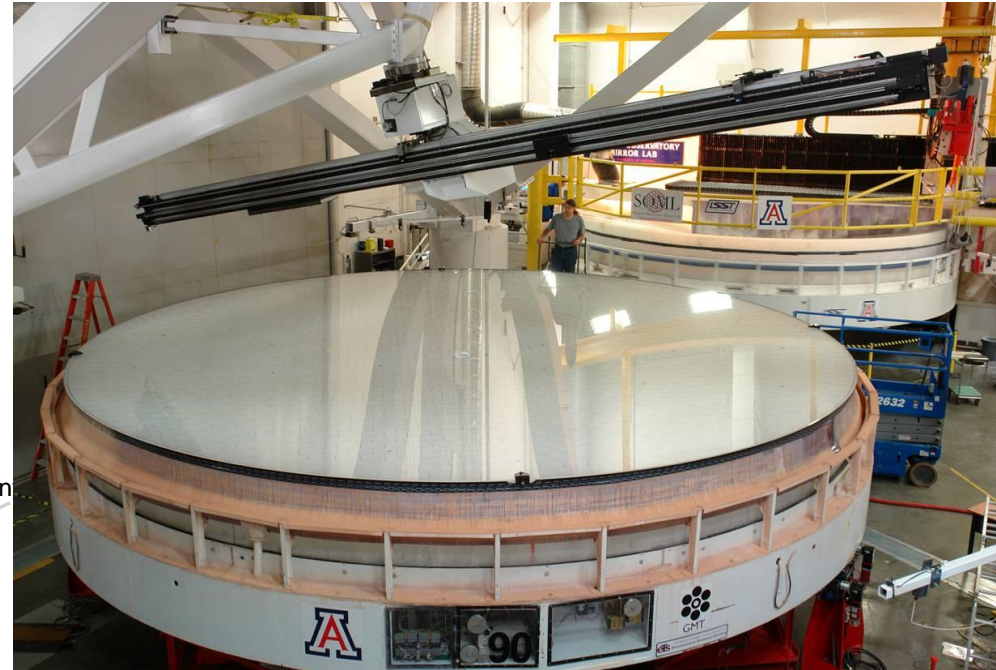
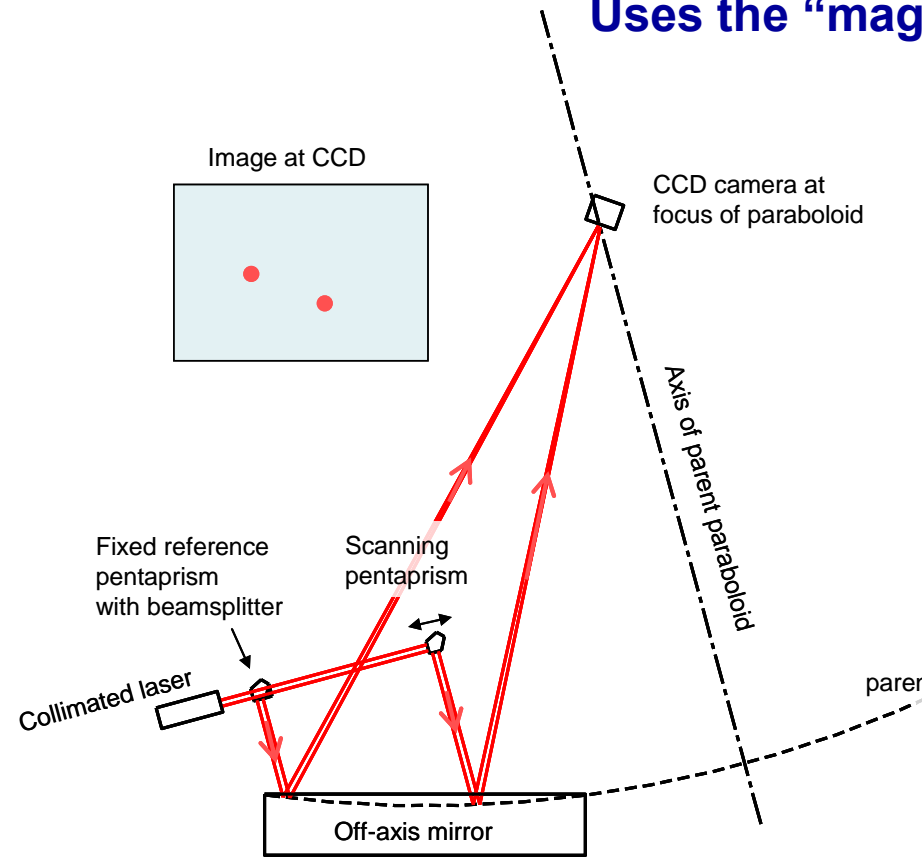
100430 GMT1 plus0avg\_aw morphed-PTFA



# Scanning pentaprism test

Uses the “magic” of the pentaprism

Pentaprism rail lies in plane perpendicular to parent axis.



Scanning pentaprism measures slope errors by producing collimated beams parallel to parent axis. Displacement of focused spot is measured with camera in focal plane.

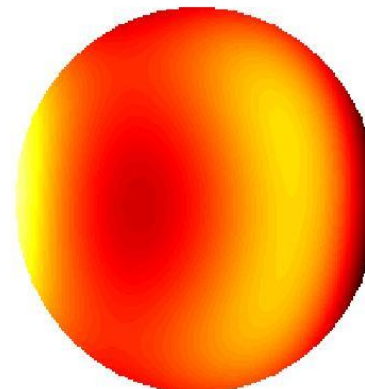
Scanning pentaprism test as implemented for GMT off-axis segments. Pentaprism rail is suspended from tower.

- 1/5 scale GMT pentaprism test (f/0.7 off axis paraboloid)
- The pentaprism test only samples lowest order aberrations
- The PP results corroborate the results from interferometry!

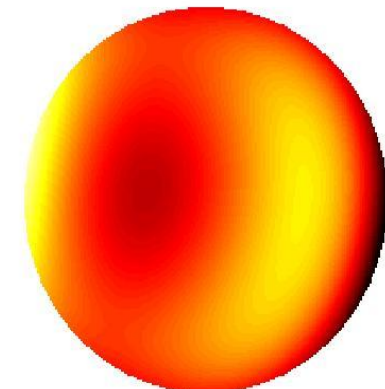


interferometric test

pentaprism measurement



102 nm rms



113 nm rms



(Peng Su)

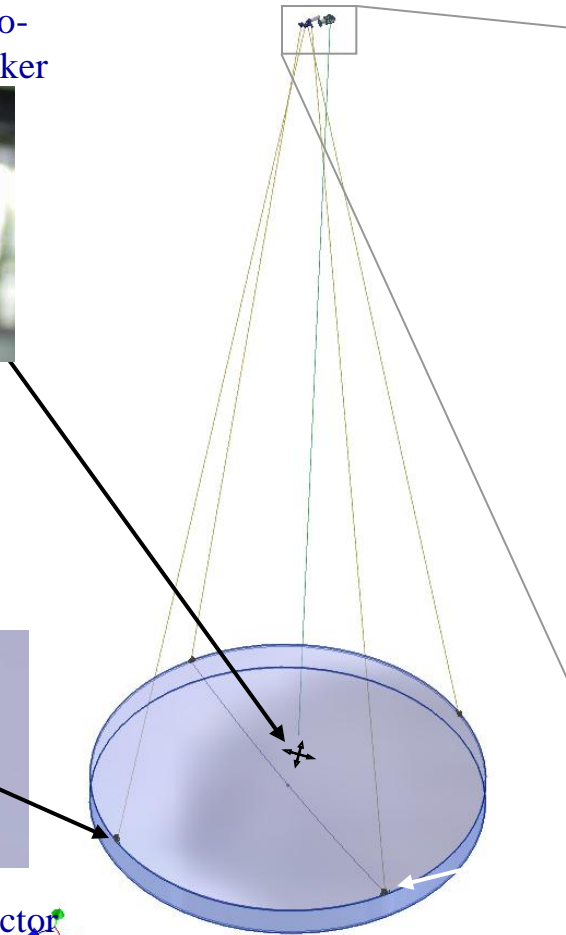


# Laser Tracker Plus

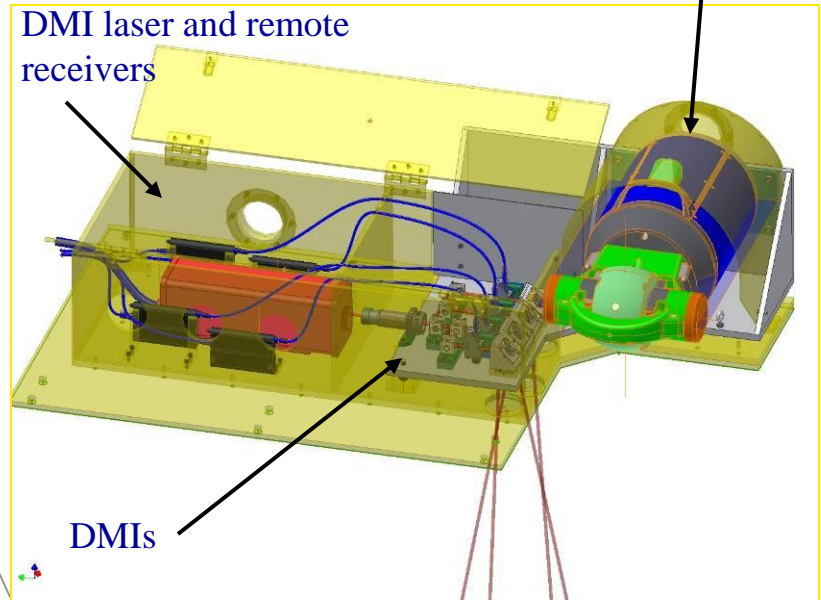
## Guide initial figuring

laser tracker & distance-measuring  
interferometers (DMI)

sphere-mounted retro-  
reflector for laser tracker

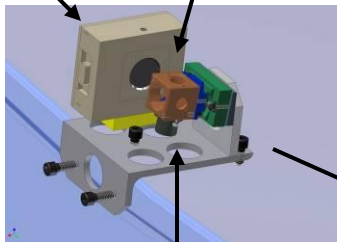


laser tracker



PSD

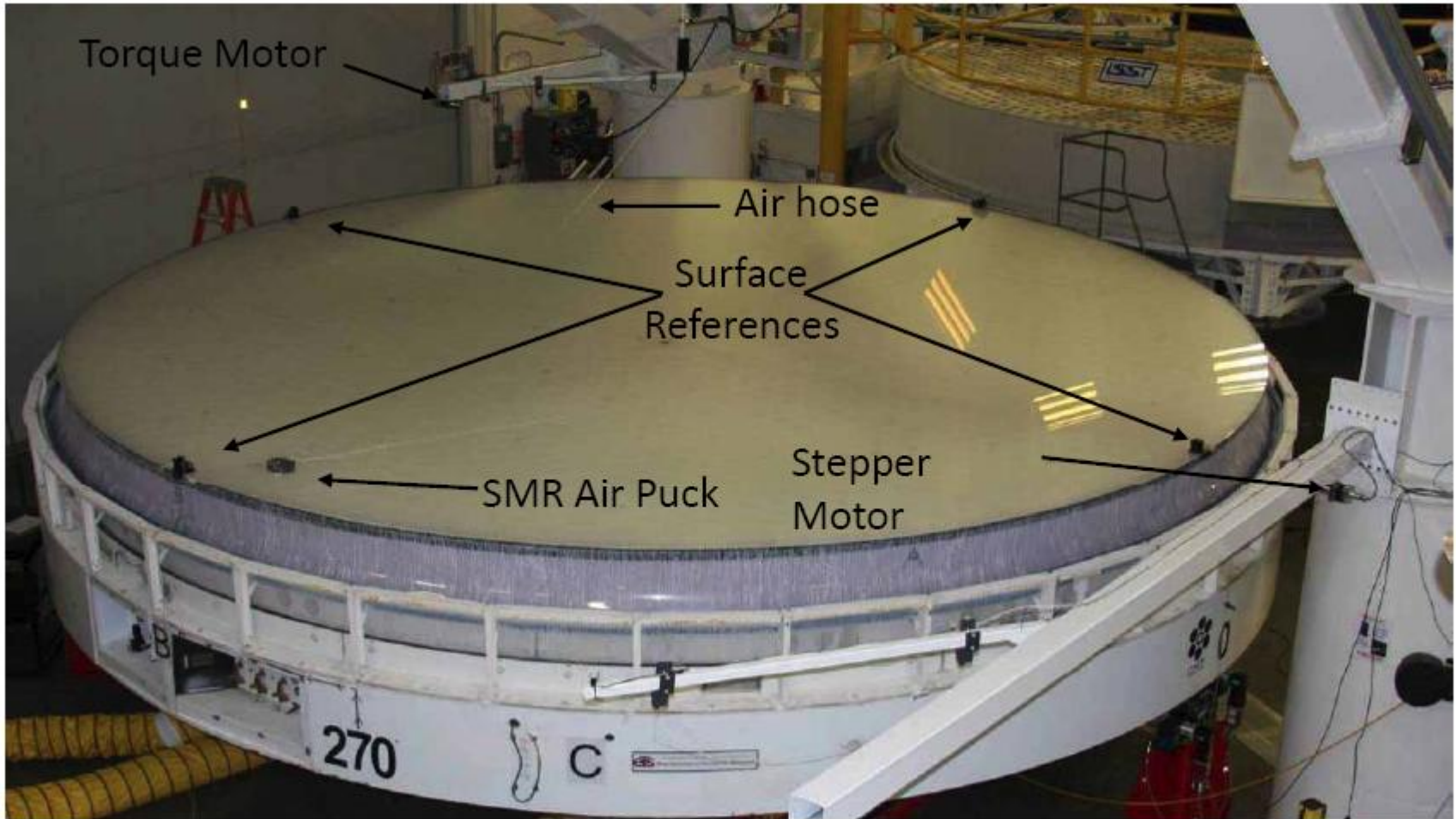
10% BS



DMI retroreflector

Retroreflector for interferometer  
and position sensing detector (PSD)  
assemblies in 4 places at edge of  
mirror

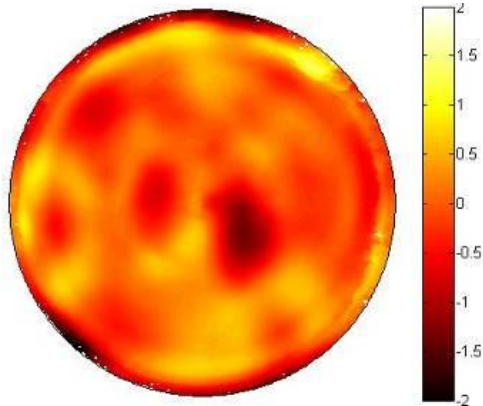
T. Zobrist



GMT segment during a measurement with Laser Tracker Plus system

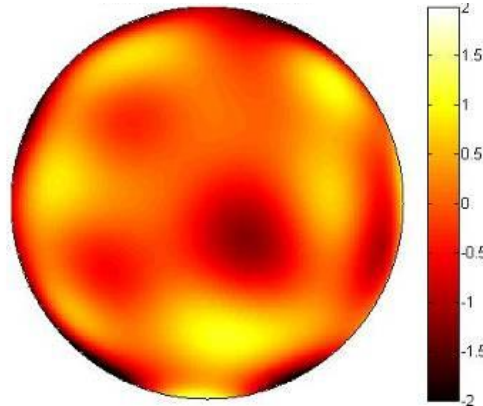
# Comparison of Laser Tracker with Interferometer

Interferometry



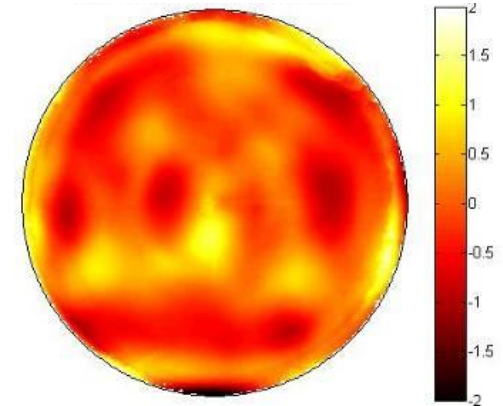
0.44  $\mu\text{m rms}$

Laser Tracker  
(200 point sample)



0.53  $\mu\text{m rms}$

Difference



0.48  $\mu\text{m rms}$

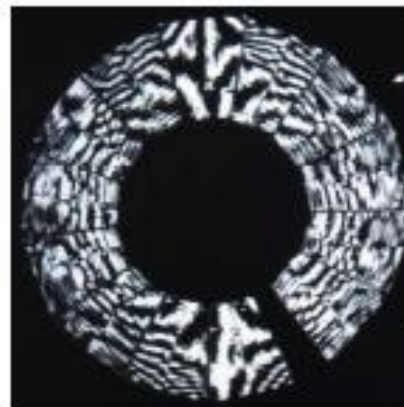
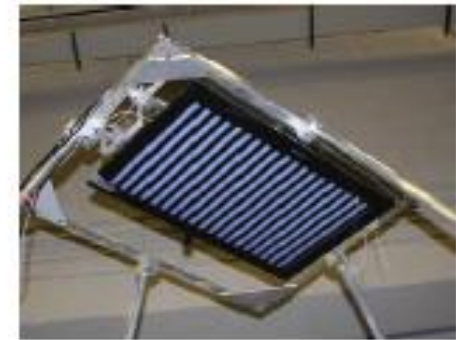
Concept from Roger Angel for measuring solar reflectors

Applied to GMT measurements (Peng Su, Bob Parks, Tom Zobrist)

Uses simple technology –  
LCD screen and CCD camera

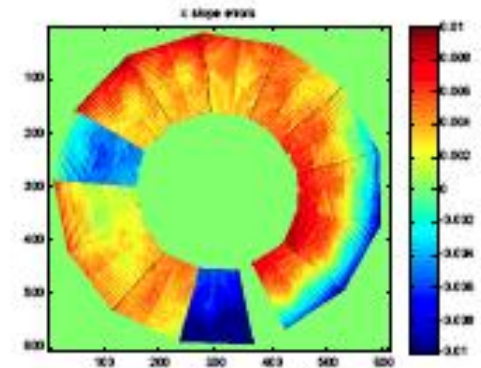


UA President Shelton, Congresswoman Giffords and Prof. Angel beside collector



Camera view of grid pattern

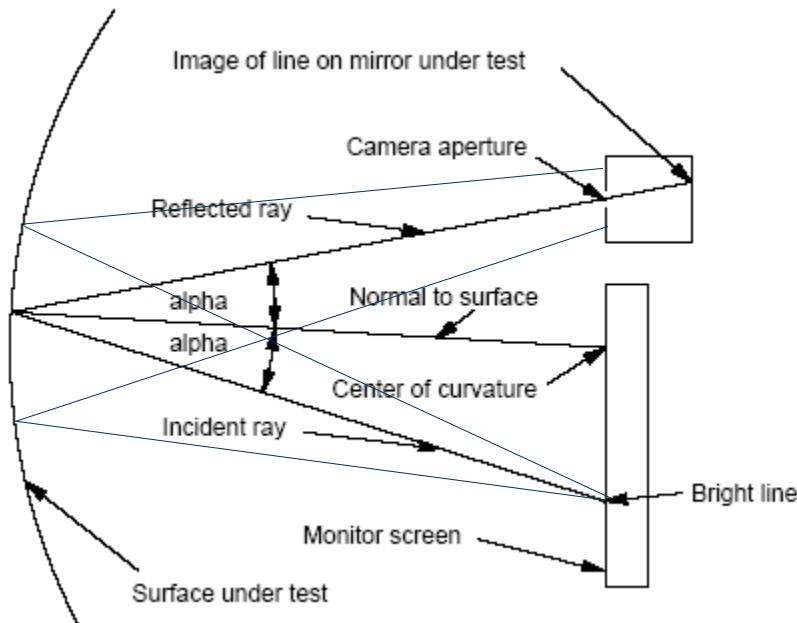
Display grid pattern



Collector slope data

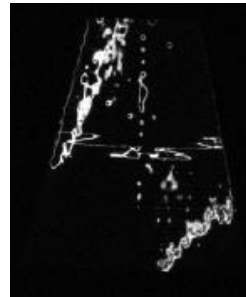
## Measurement Principle

- SCOTS measures slope variations by looking at the reflection of a screen (computer monitor) from the surface under measurement.
- The measurement brightness variations are used to calculate surface slopes
- Integrate slope maps to get full surface maps

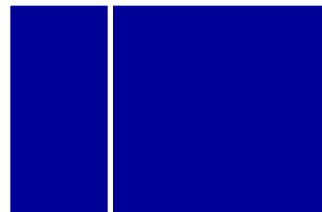


### Line scanning

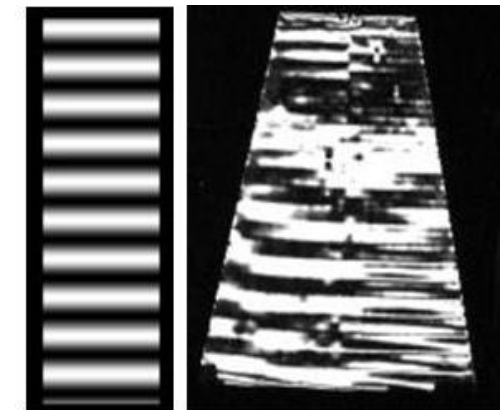
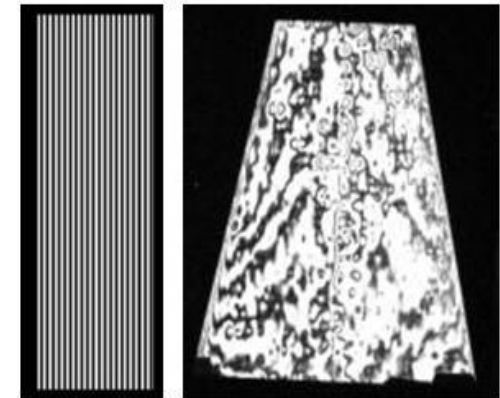
Image at CCD



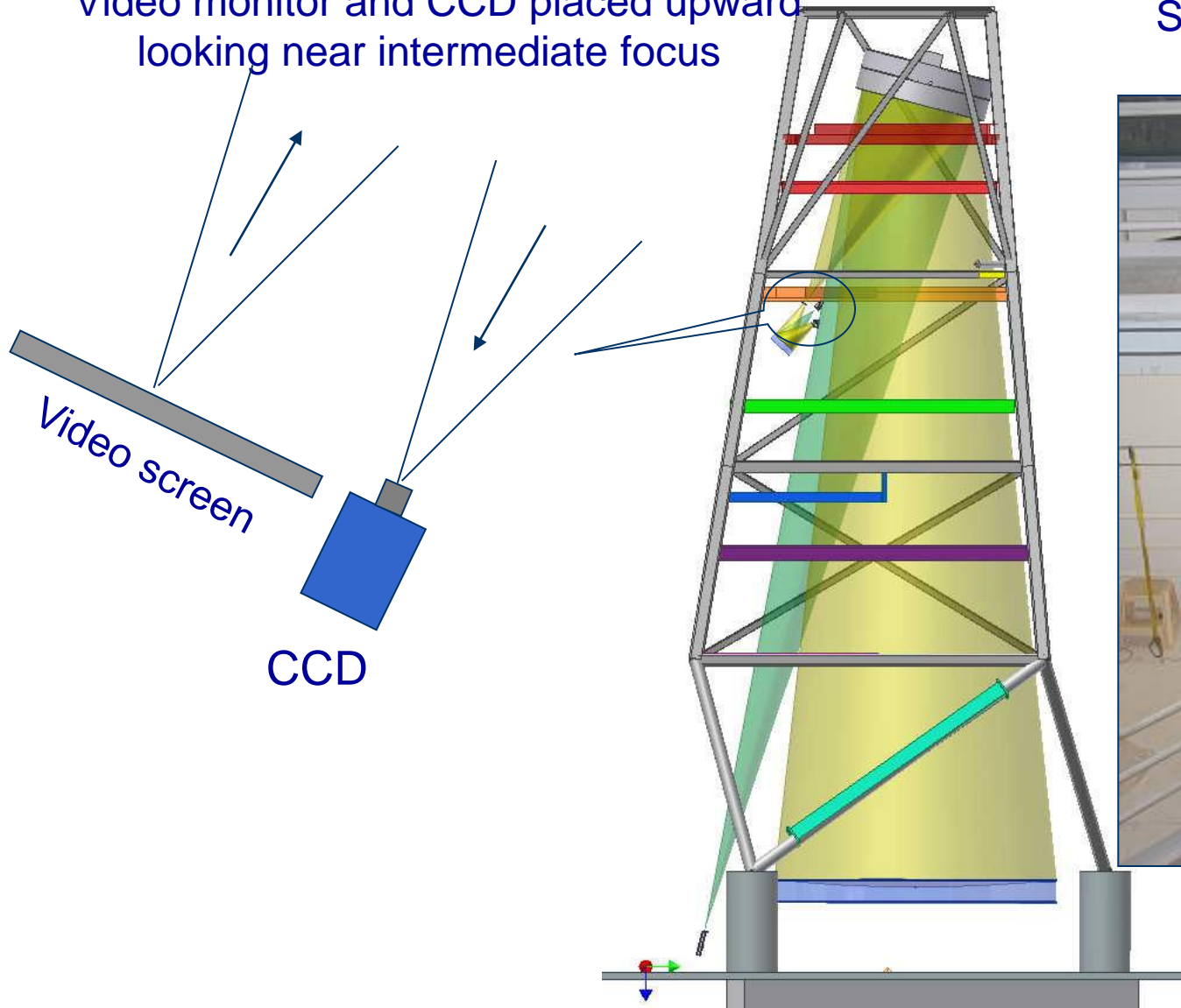
Monitor image



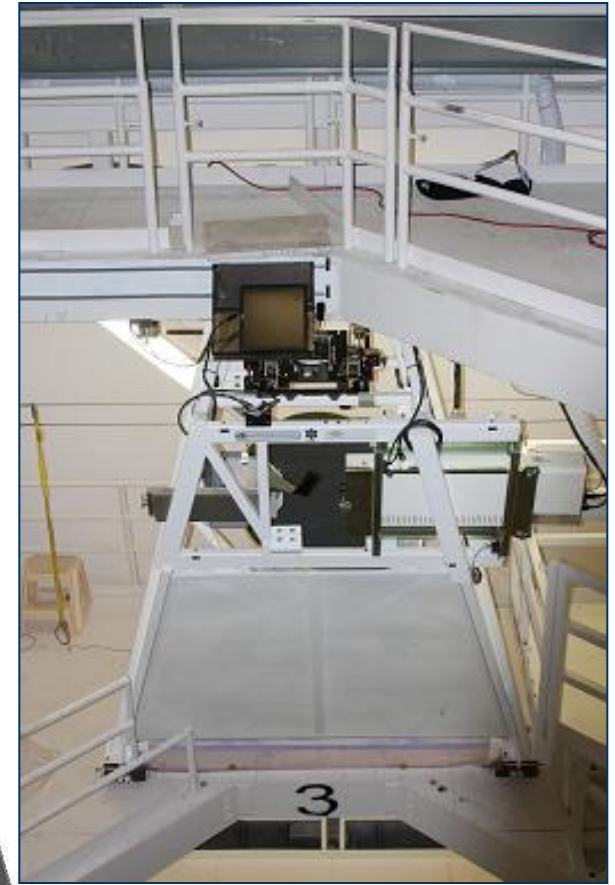
### Fringe projection



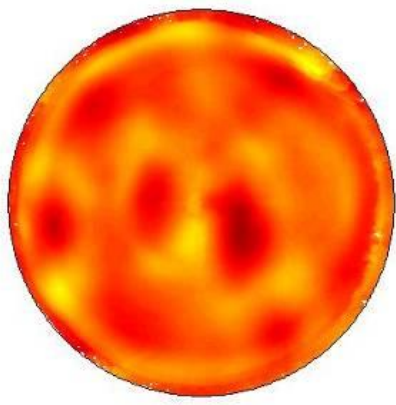
Uses reflection from large fold sphere  
Video monitor and CCD placed upward  
looking near intermediate focus



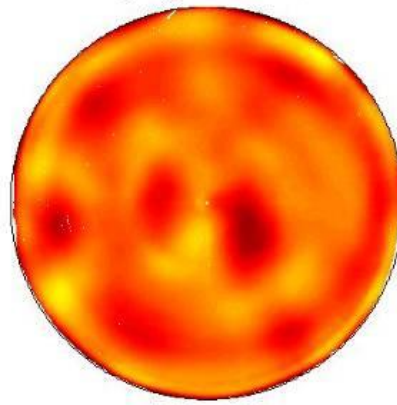
Looking down at Sam and  
SCOTS



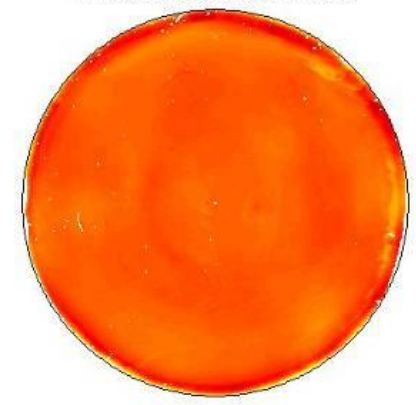
## Wow!



Principal test  
21 polynomials subtracted  
0.32  $\mu\text{m}$  rms



SCOTS  
21 polynomials subtracted  
0.35  $\mu\text{m}$  rms



difference  
0.16  $\mu\text{m}$  rms

All maps show surface error in microns. Circle indicates 8.4 m diameter.

- Uses proven mirror technology
- Challenges of optical testing has been solved
- Primary segment #1 nearing completion
- The casting of the second primary mirror segment is currently being planned





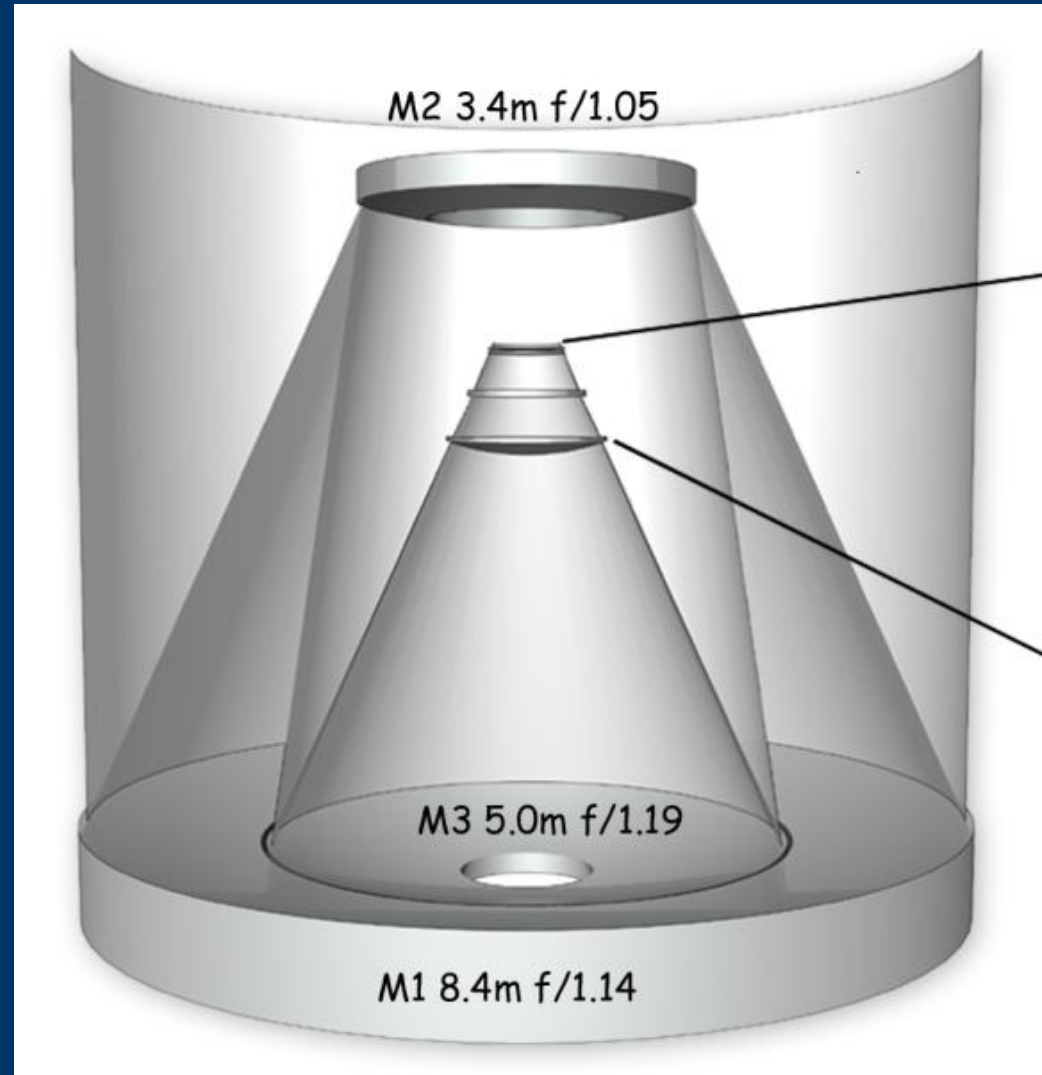
8.4-m aperture

Uses three-mirror design to attain  
 $3.5^\circ$  field of view

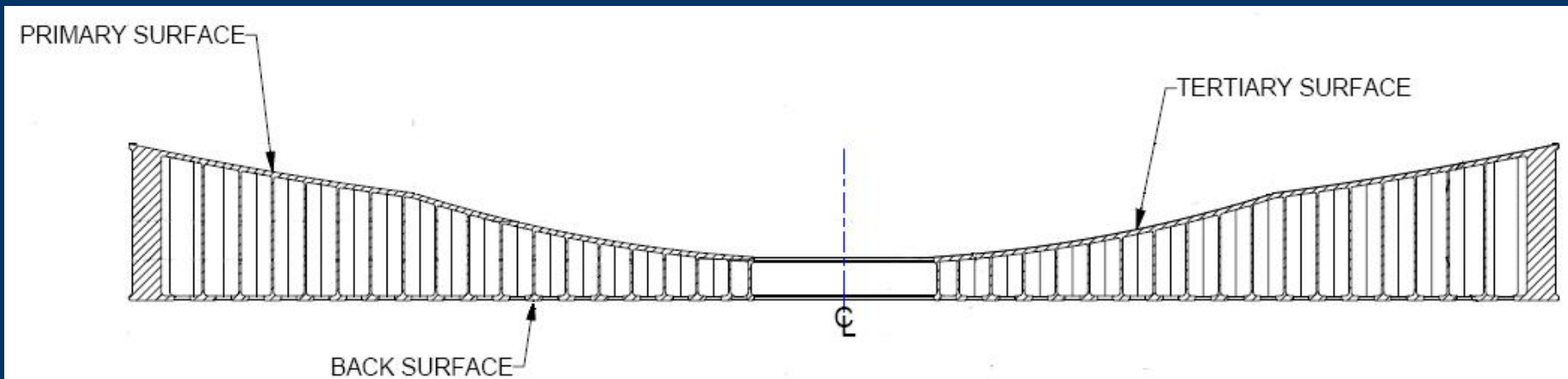
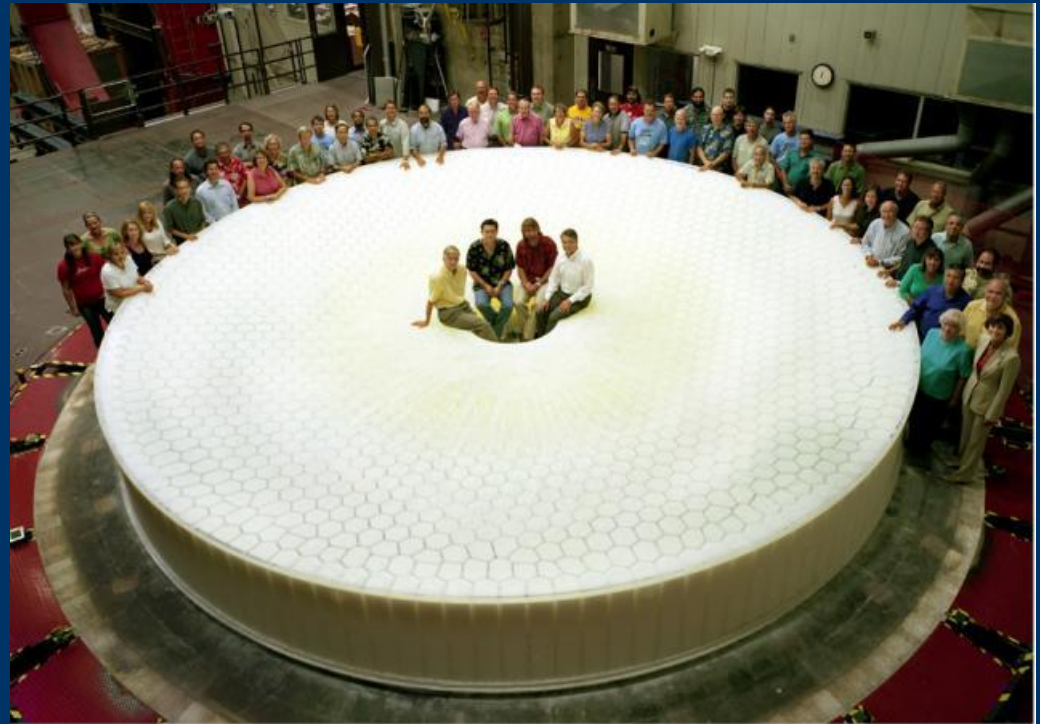
15-sec exposures to survey the sky

30TB of data per night!

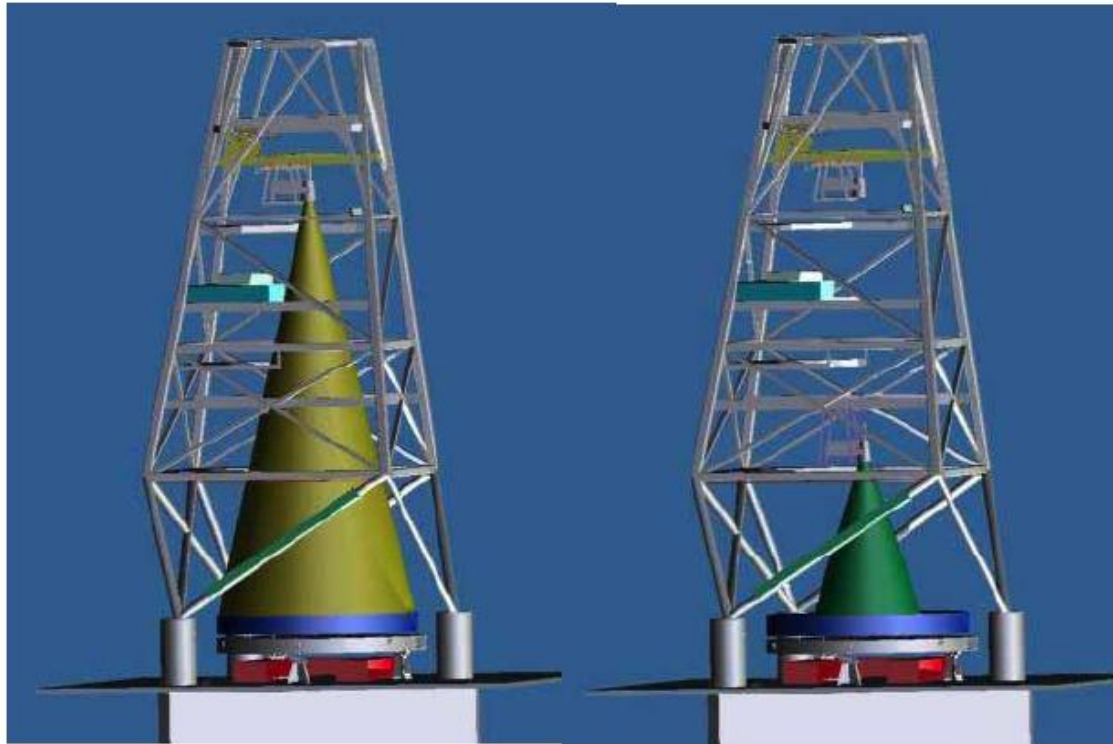
Plan for 2016 operation in Chile



- Spin cast blank at UA
- PM curvature from spinning, TM shape cut in with diamond generated



# Null test of M1, M3



Configuration for test of M1  
 $R = 19.8 \text{ m}$

Configuration for test of M3  
 $R = 8.3 \text{ m}$

Separate interferometric optical tests being developed for TM and PM

Each test is aligned to mirror using two methods:

- Laser tracker
- Projected references from computer generated holograms

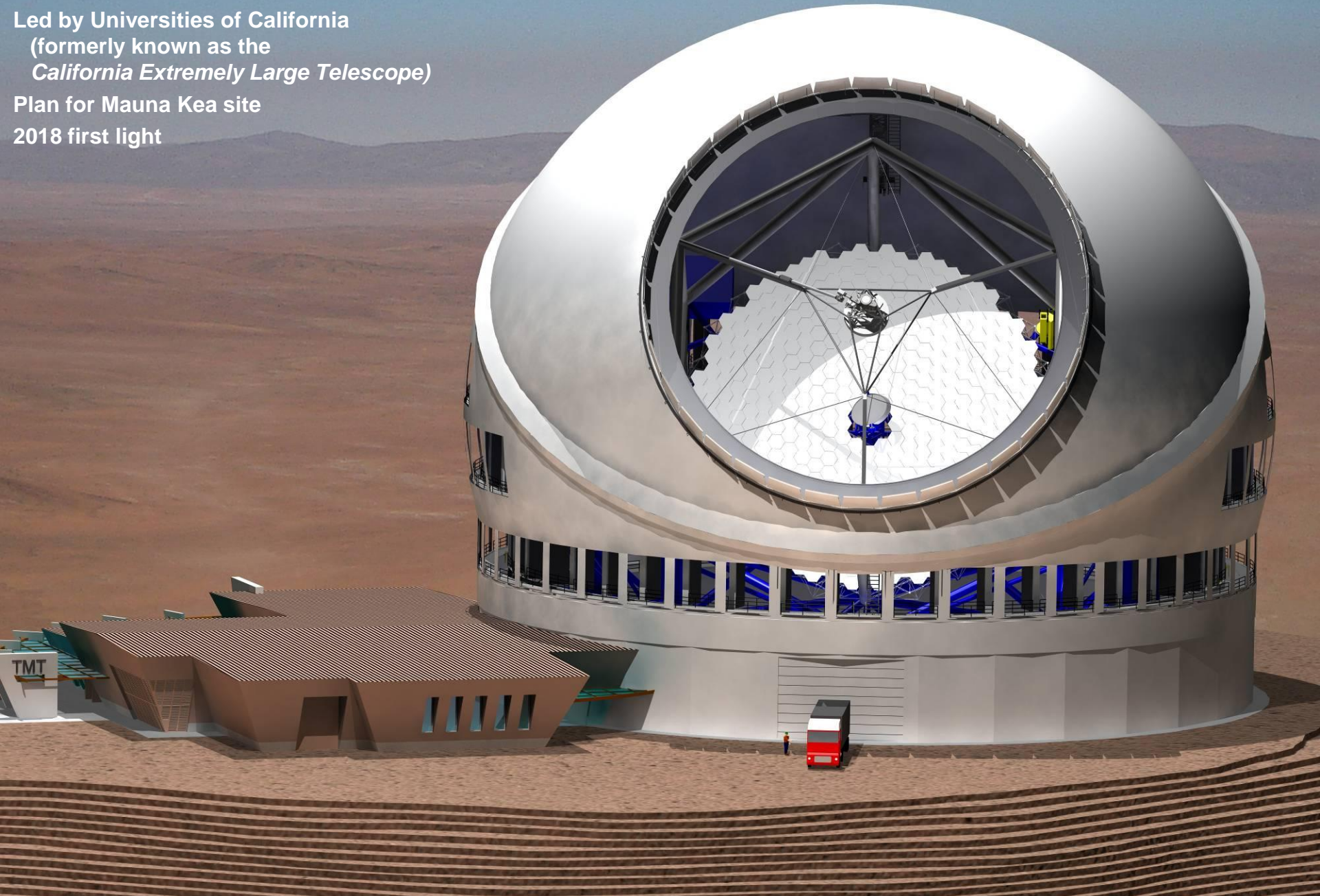
Both sets of test optics are deployed on trolleys, can be removed to avoid obscuring views from other test equipment.

# The Thirty Meter Telescope

Led by Universities of California  
(formerly known as the  
*California Extremely Large Telescope*)

Plan for Mauna Kea site

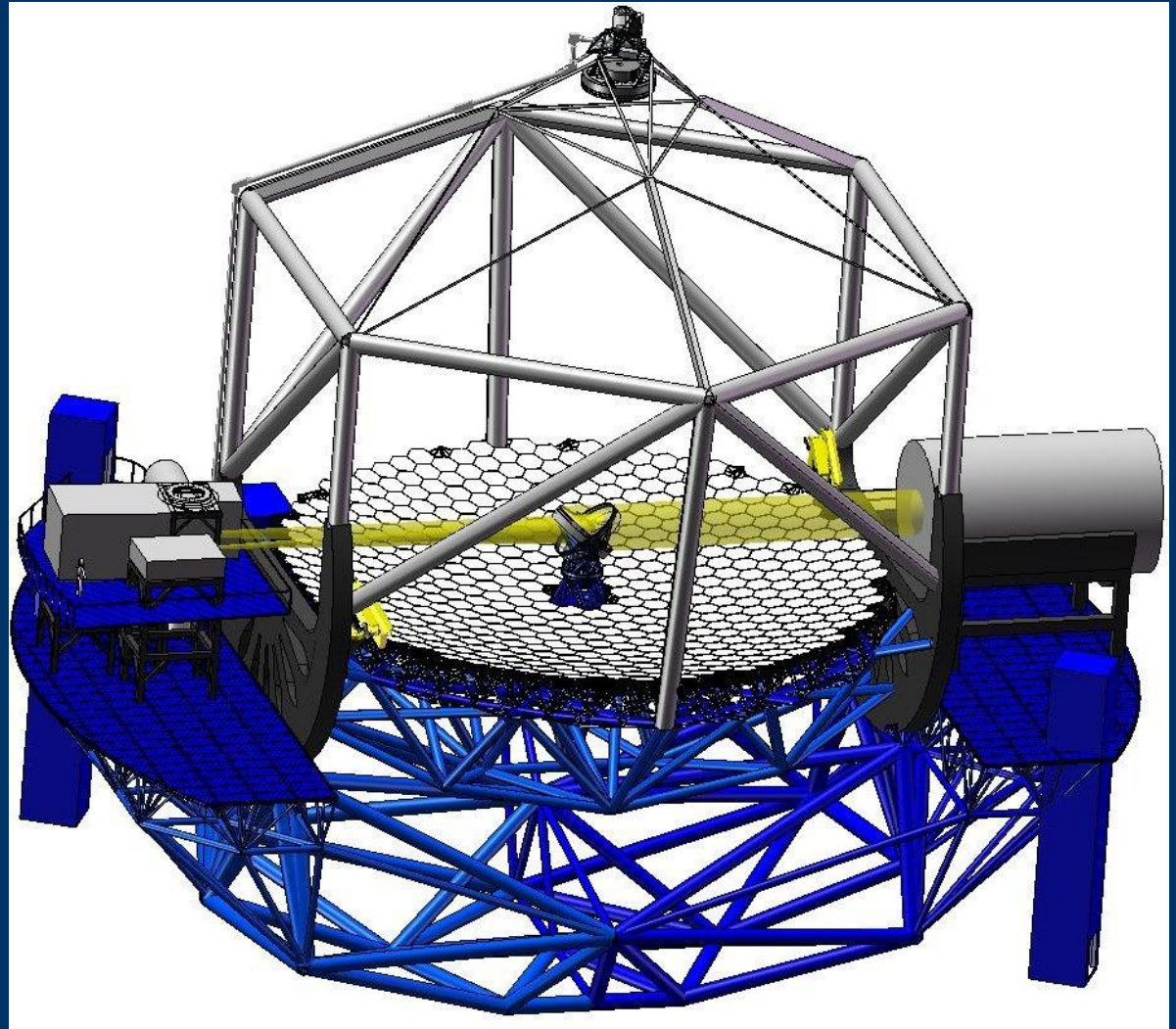
2018 first light



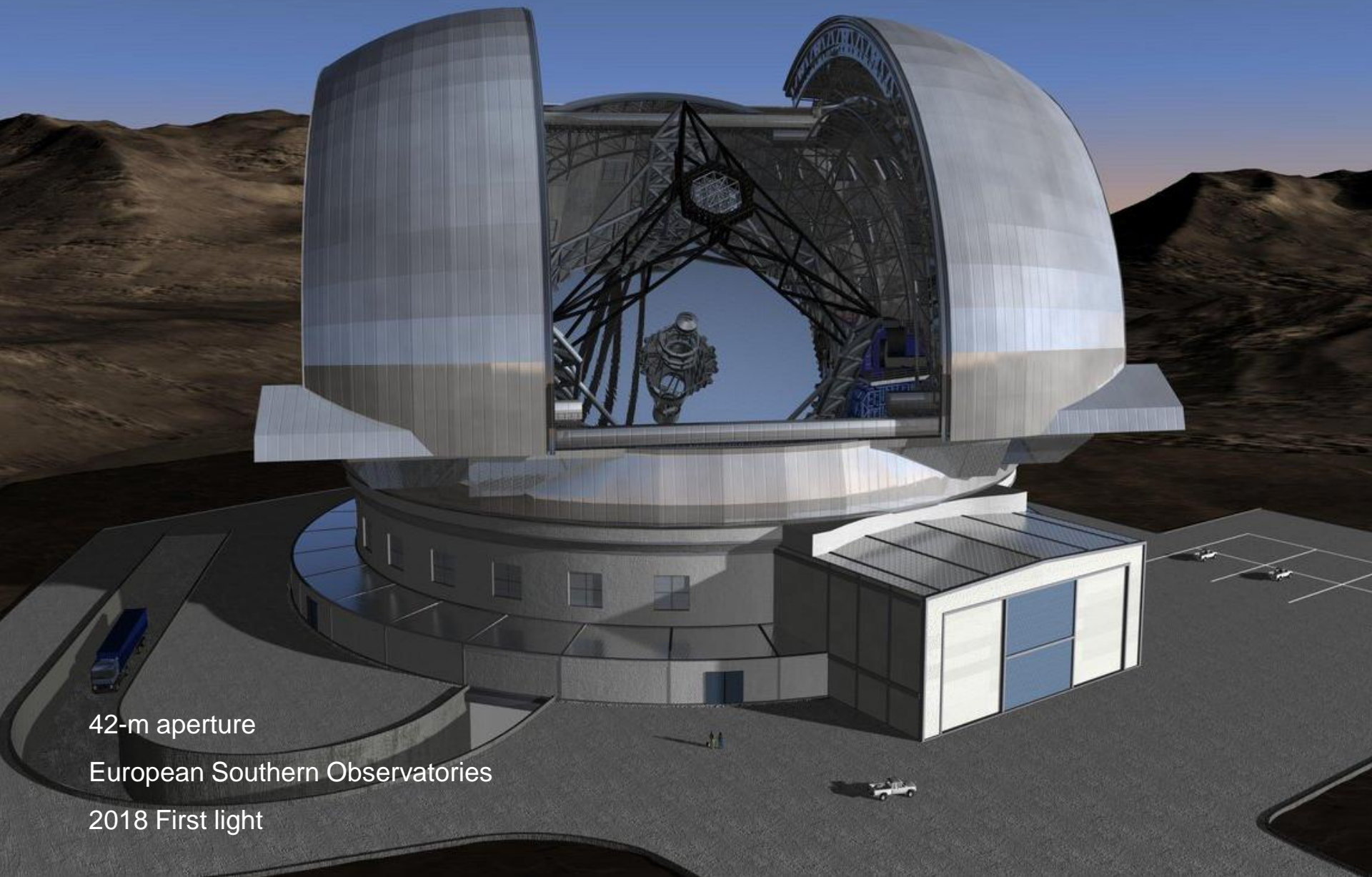
3.1-m convex  
secondary mirror

3.5-m flat  
tertiary mirror

30 meter f/1 primary  
mirror, made of 492  
hexagonal segments



# The European Extremely Large Telescope



42-m aperture

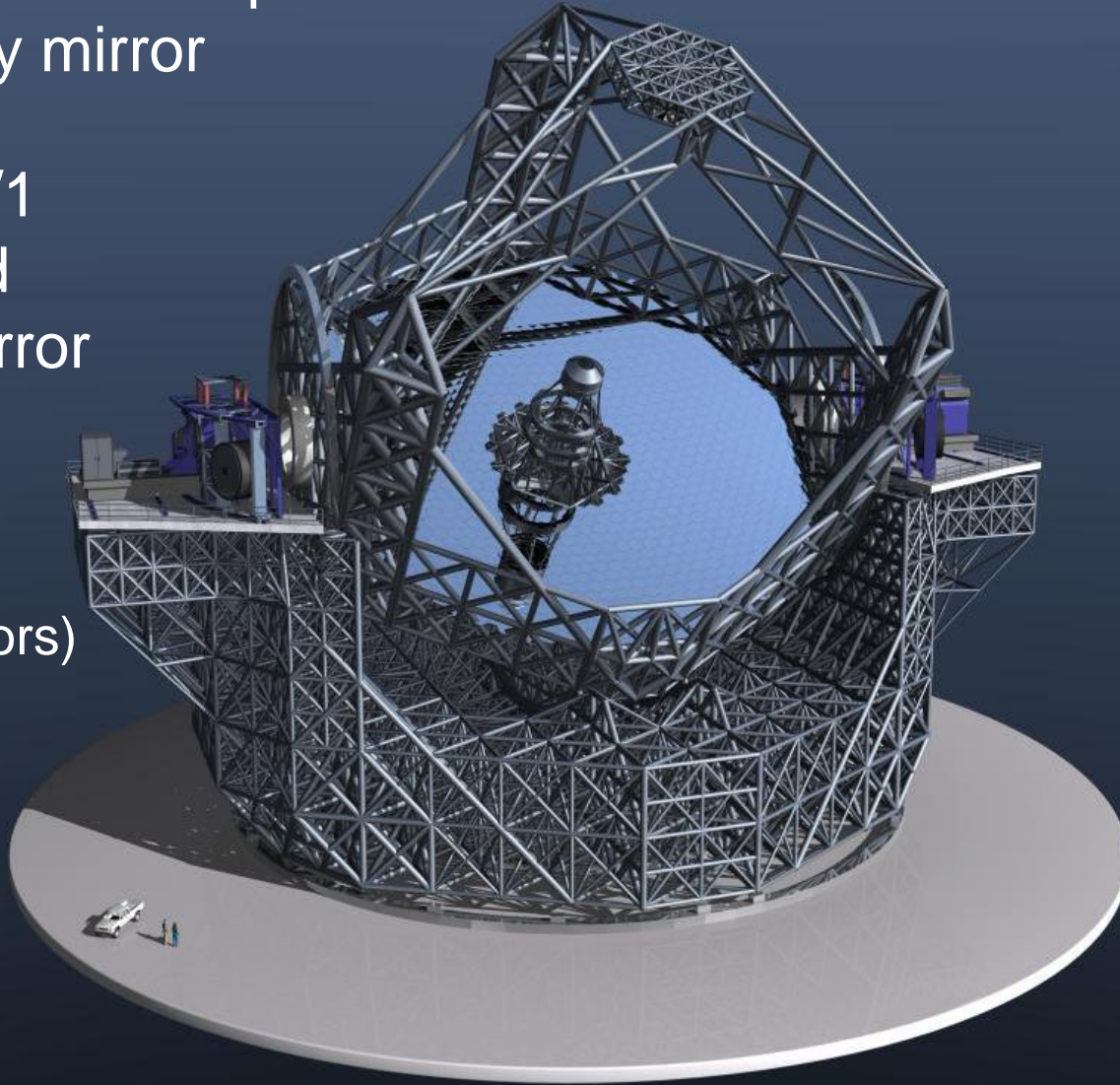
European Southern Observatories

2018 First light

6 meter convex aspheric  
secondary mirror

42-meter f/1  
segmented  
primary mirror

(plus other mirrors)



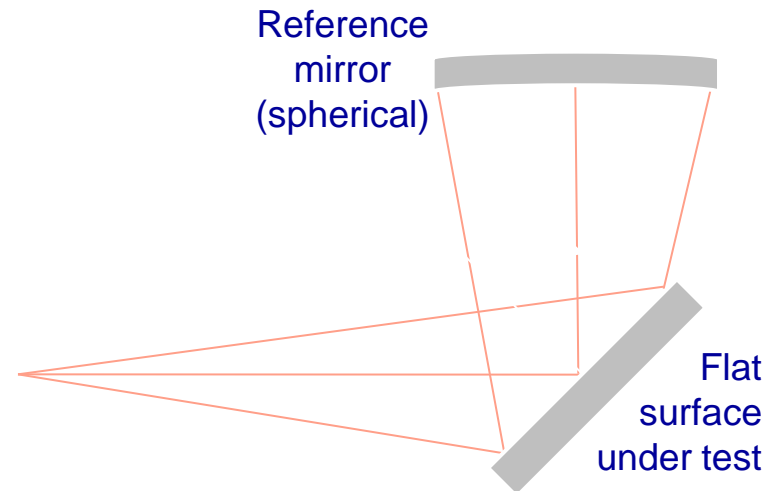
# Measurement of large flat mirrors



TMT tertiary:

Flat mirror: 3.5 x 2.5 meter

Conventional test of large flats uses  
Ritchey-Common test, not practical

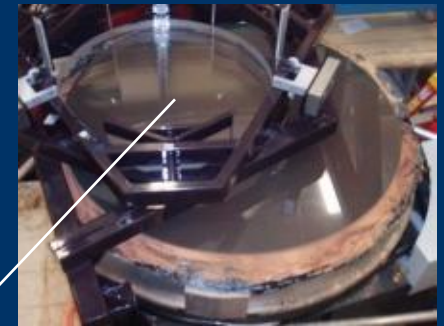
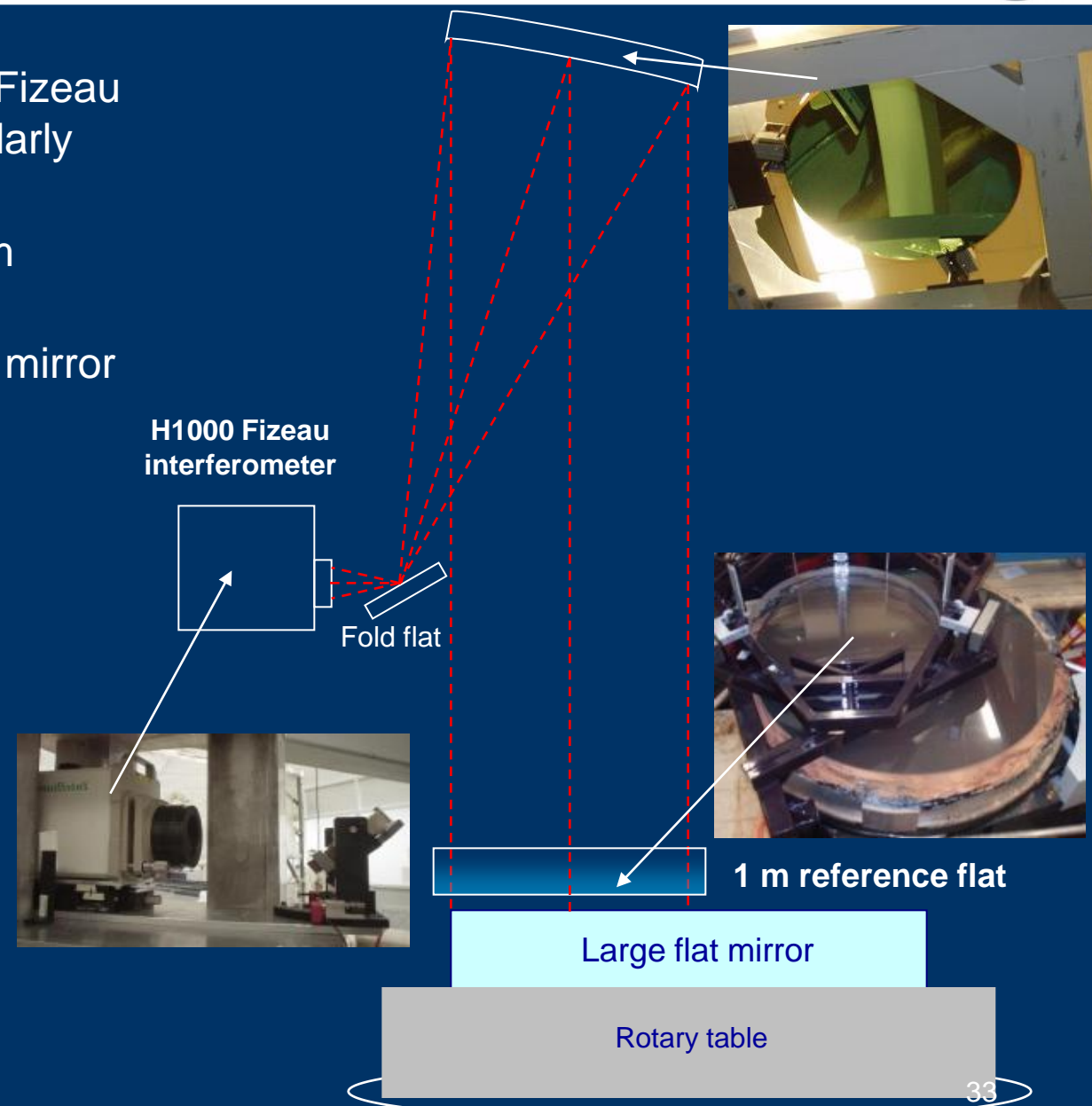
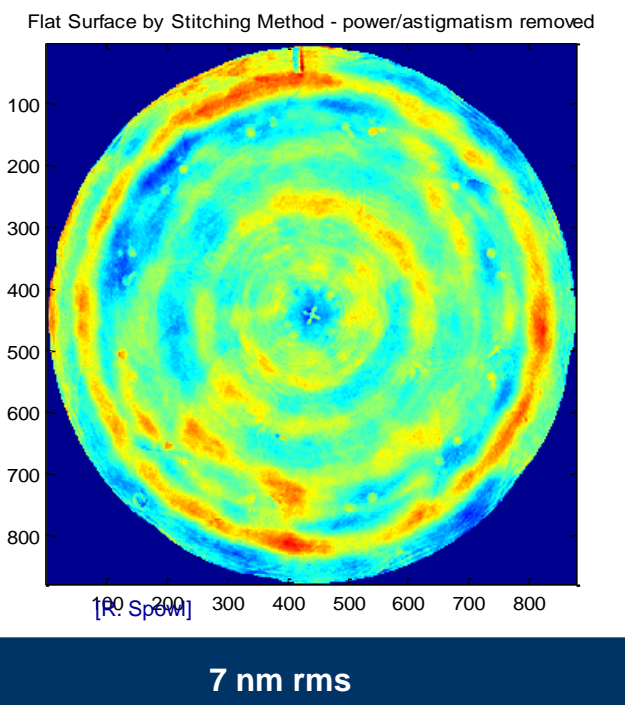


Measurement difficulties are solved by technologies  
developed and proven at UA



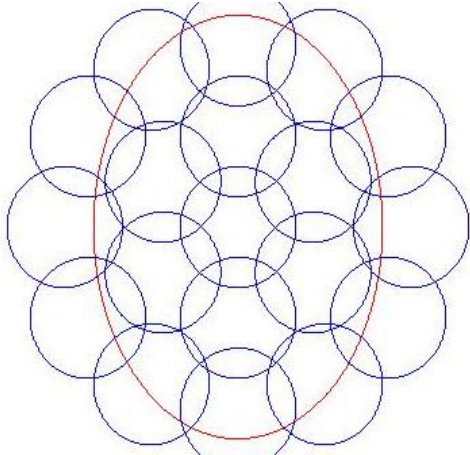
# 1-m vibration insensitive interferometer

- Commercial instantaneous Fizeau interferometer (uses 2 circularly polarized beams)
- Modified to use external 1-m reference
- Demonstrated on 1.6-m flat mirror
- World's best large flat!

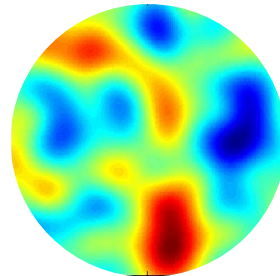


# UA Fizeau test for TMT tertiary

Layout of subapertures

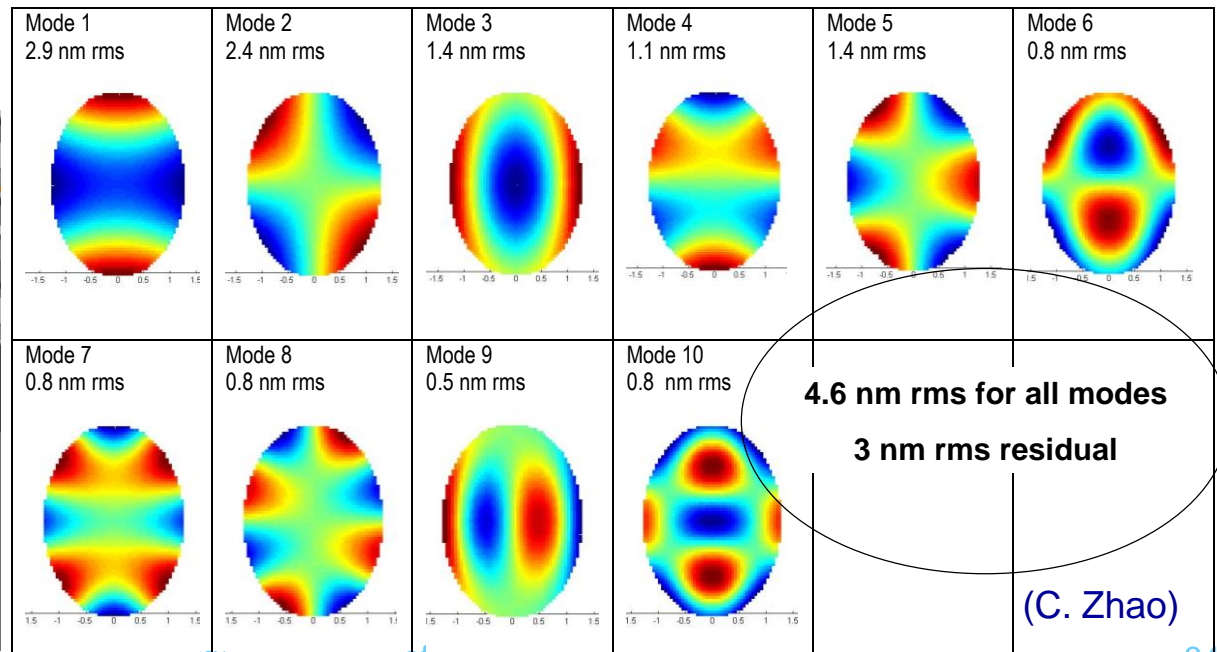
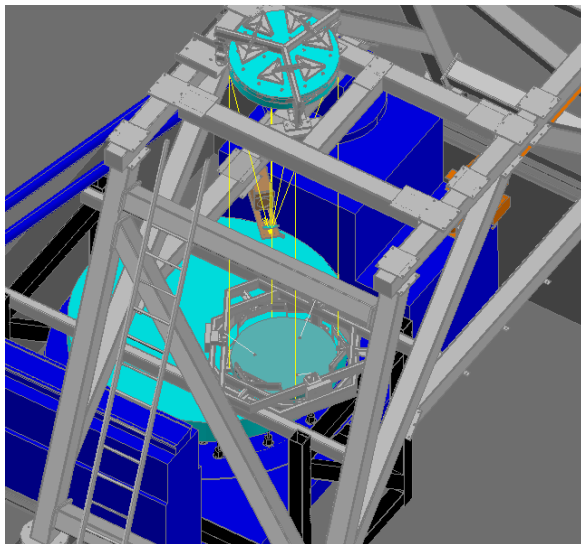


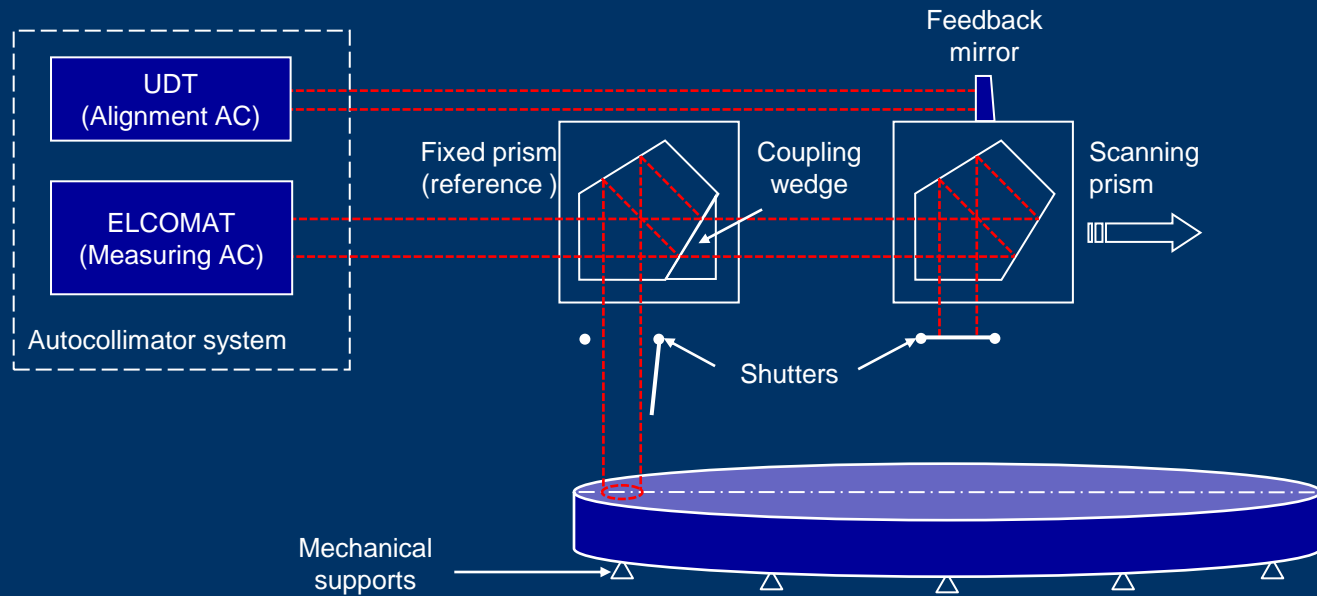
3 nm rms typical measurement noise



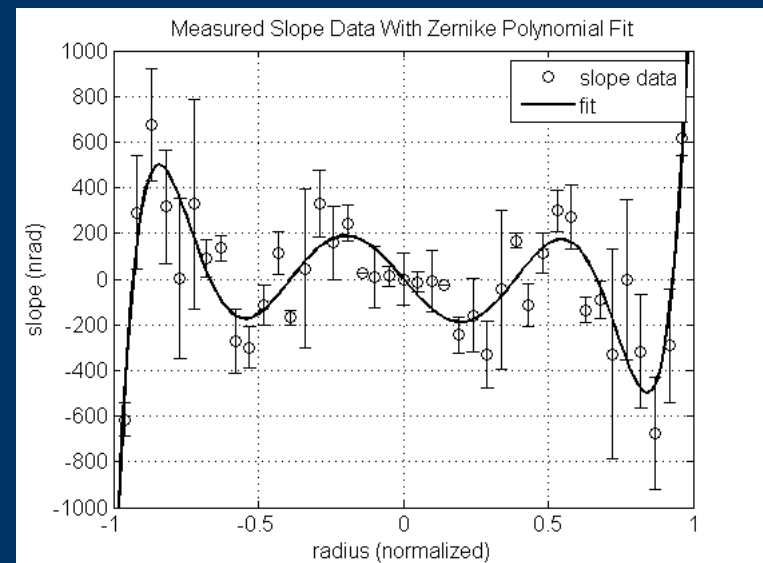
Monte Carlo analysis to evaluate coupling of alignment, noise to surface reconstruction

5.5 nm rms measurement accuracy with proven UA hardware!

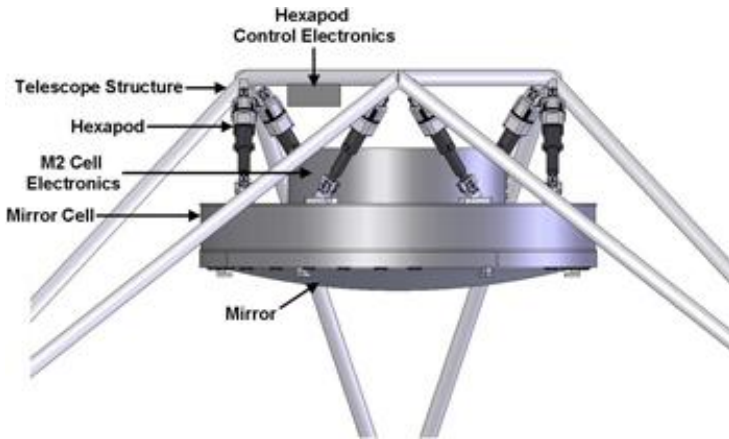




- Demonstrated performance is  $0.2 \mu\text{rad rms}$
- Power measurement for 1.6-m flat was 11 nm rms



TMT secondary mirror in telescope



## Convex secondary mirrors

TMT secondary: 3.1-m

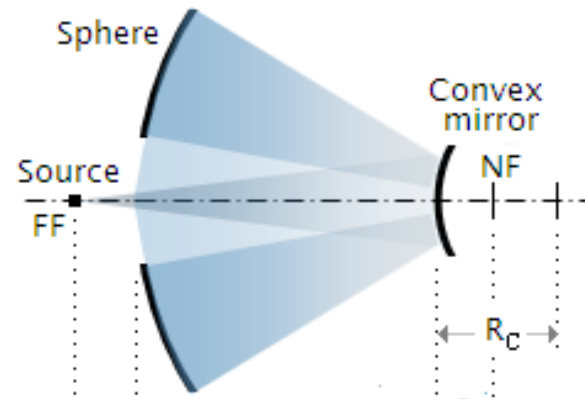
LSST secondary: 3.4-m

E-ELT secondary: 6-m

Conventional test of such mirrors uses the Hindle test, not practical at these sizes

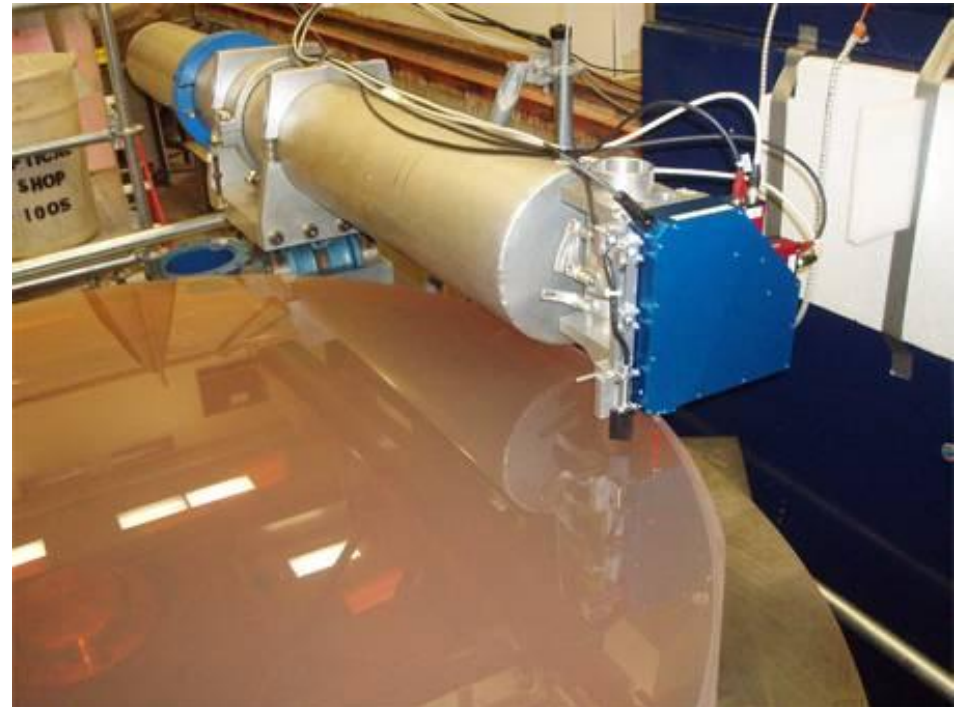
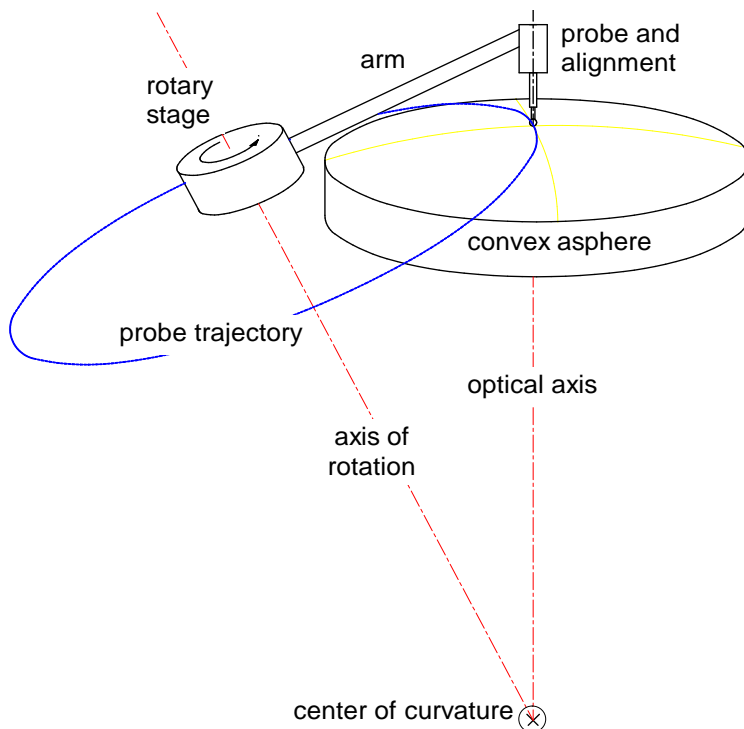


LSST SM blank : ULE

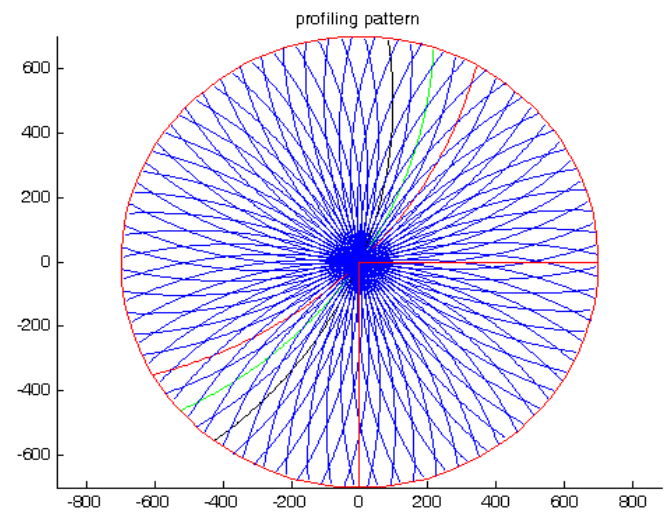


# Swingarm Optical CMM

- Scans surface with optical displacement probe
- Continuous arc scans create profiles
- Profiles stitched together to give surface maps
- Works for convex or concave surface

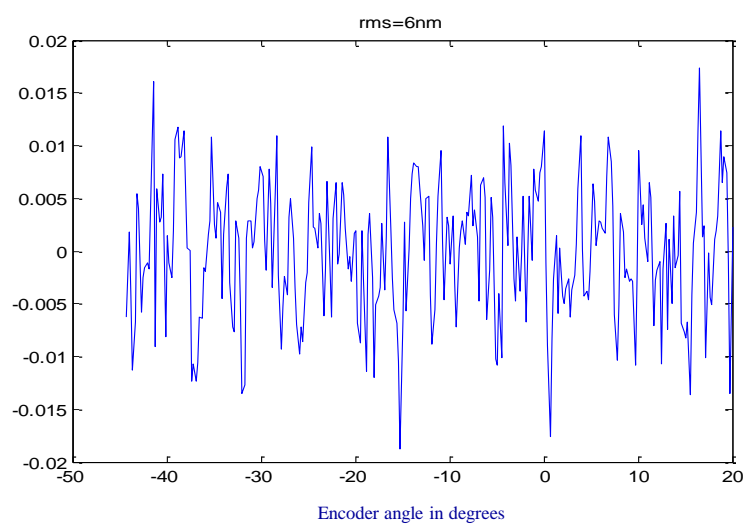


**Pattern of 64 scans**

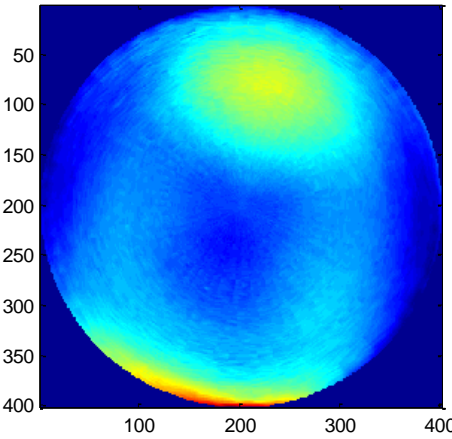


Surface  
 measurement  
 in  $\mu\text{m}$

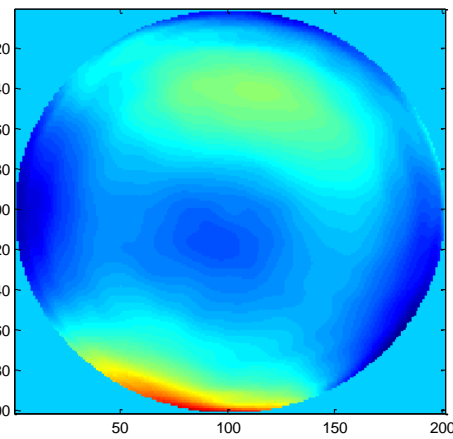
**Repeatability ~ 6 nm rms/scan**



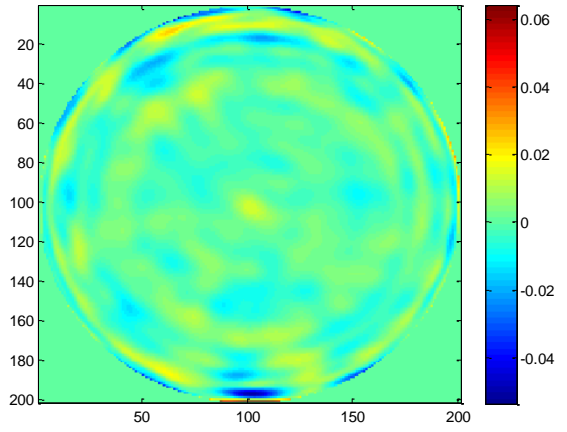
**Interpolated data  
 75 nm rms**



**896 term reconstruction  
 78 nm rms**

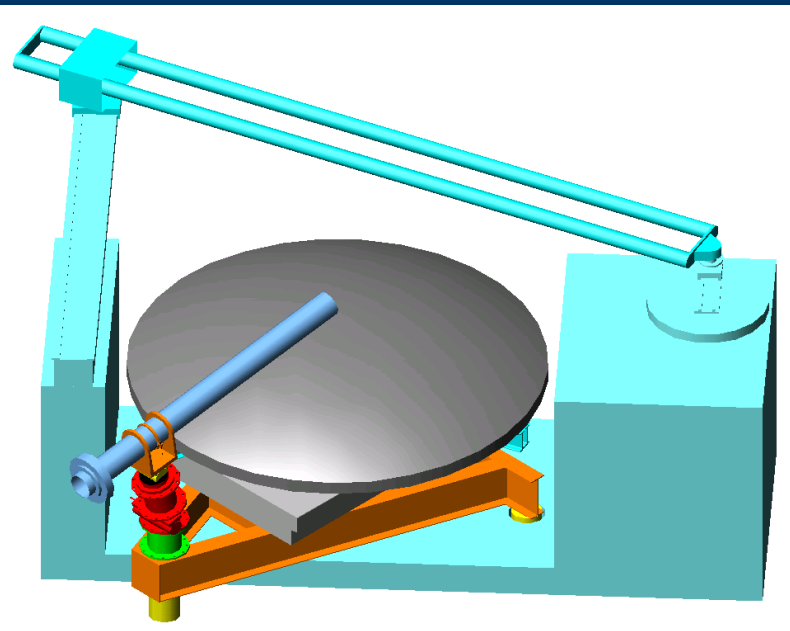


**Low order terms removed  
 6 nm rms**

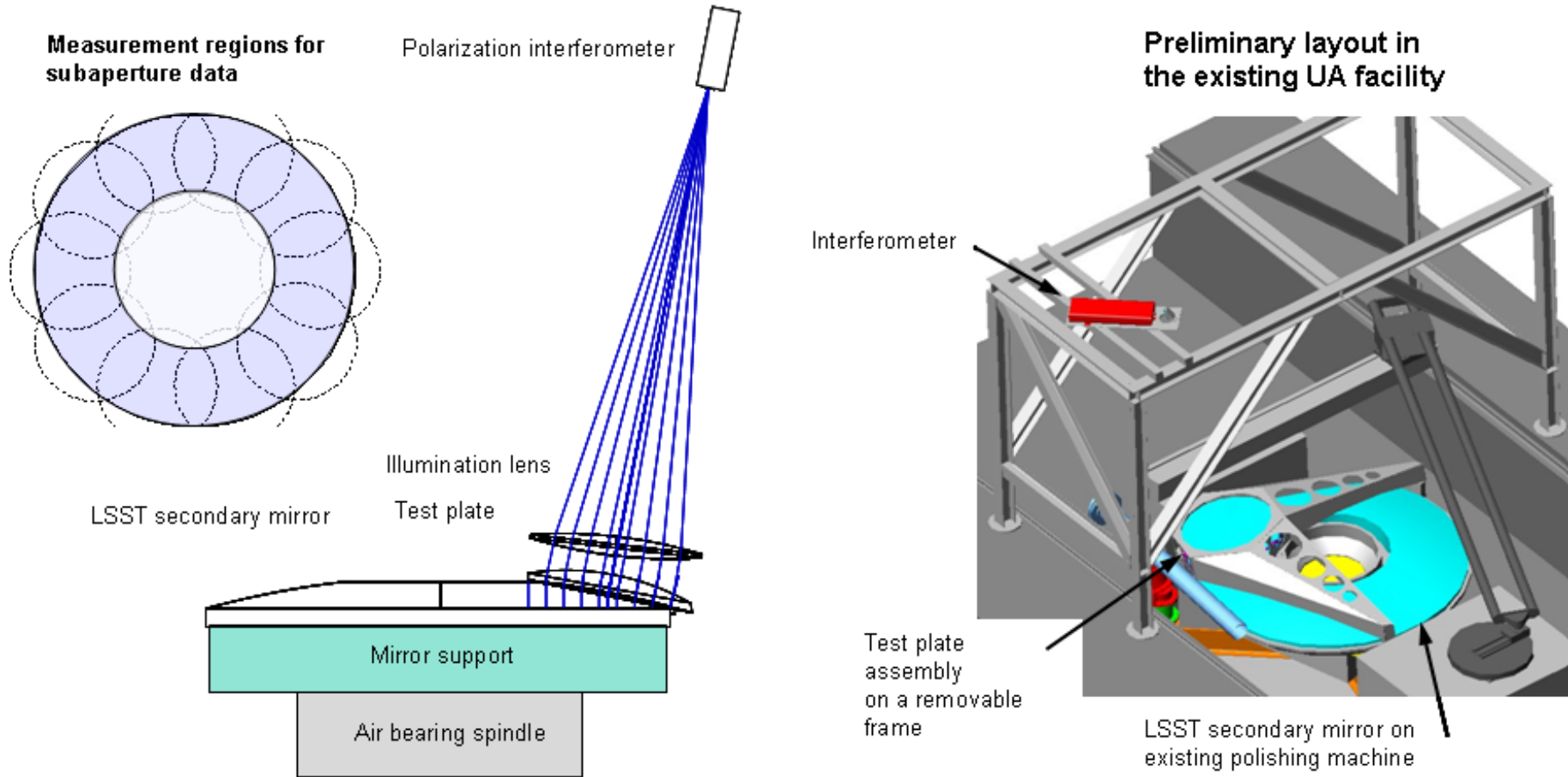


**Repeatable errors of 34 nm rms are calibrated out**

- Original system built at Optical Sciences was made with 3.8-m capacity.
- This was designed to be integrated with 4-m polishing machine
- Performance is expected to be  $< 20$  nm rms at this size



# Fizeau interferometry for large secondary mirrors

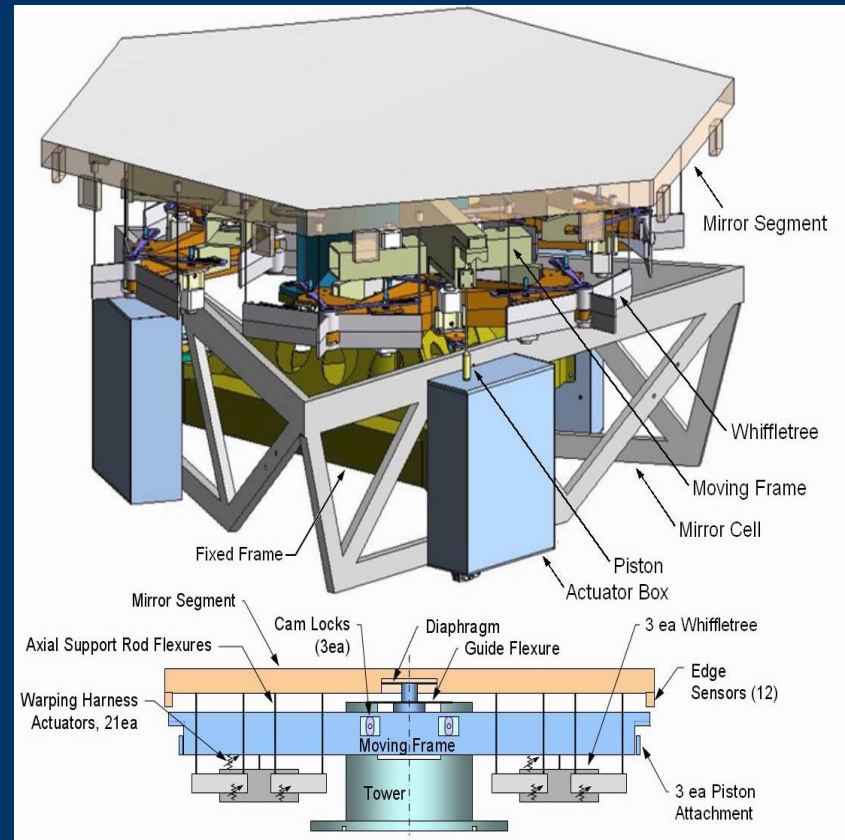
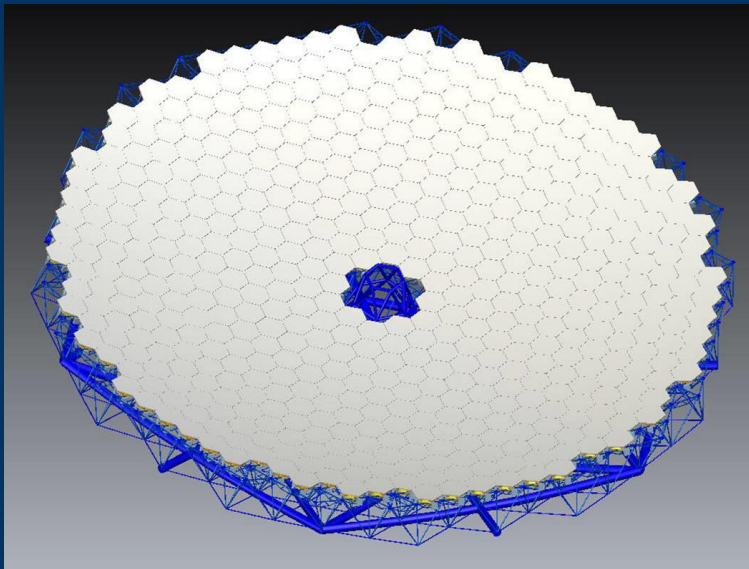


Reference surface on test plate has concave matching asphere for off axis portion of the secondary mirror

We have also developed concept for using a spherical reference, corrected with CGH



30-m f/1 near paraboloid  
492 segments

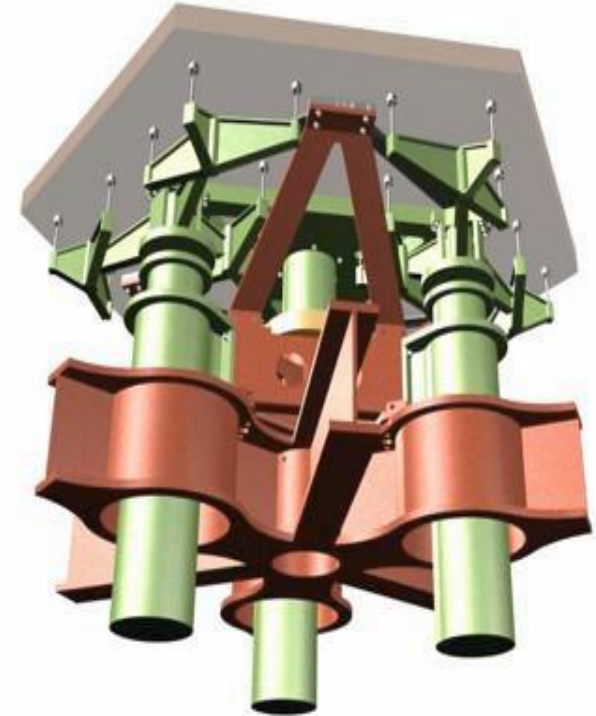
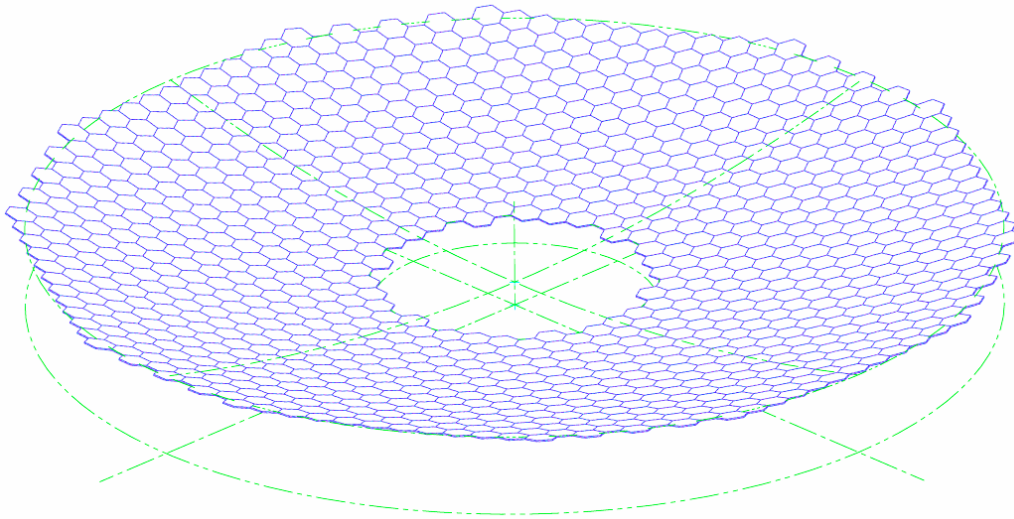


1.44-m segments, 45 mm thick

Each is supported by 27-point whiffle tree, warped with 21 actuators

Segment tip/tilt/piston adjusted with 3 position actuators, based on edge sensors

- **42-m f/1 near paraboloid**
- **984 segments**



**1.43-m segments, 50 mm thick**

**Each is supported by 18 or 27-point whiffle tree**

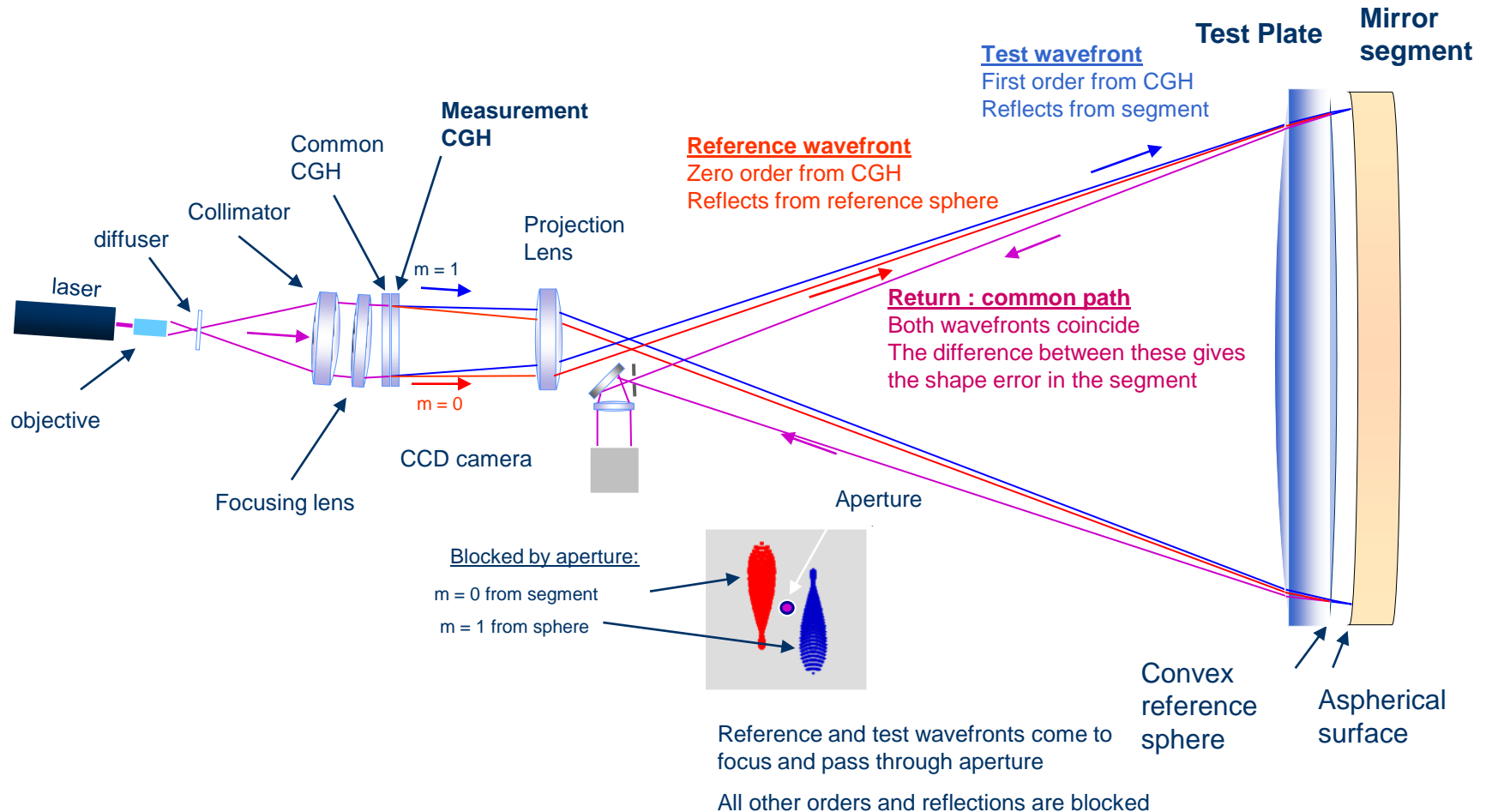
**Segment tip/tilt/piston adjusted with 3 position actuators, based on edge sensors**

- Off-axis aspheres, with different prescription (curvature changes from center to edge)
- To work together, the radius of curvature must match. Power is treated as a figure error
- Must be efficient, limiting setup, alignment, and test time
- Measurement accuracy of 5 nm rms is required

## Other important issues:

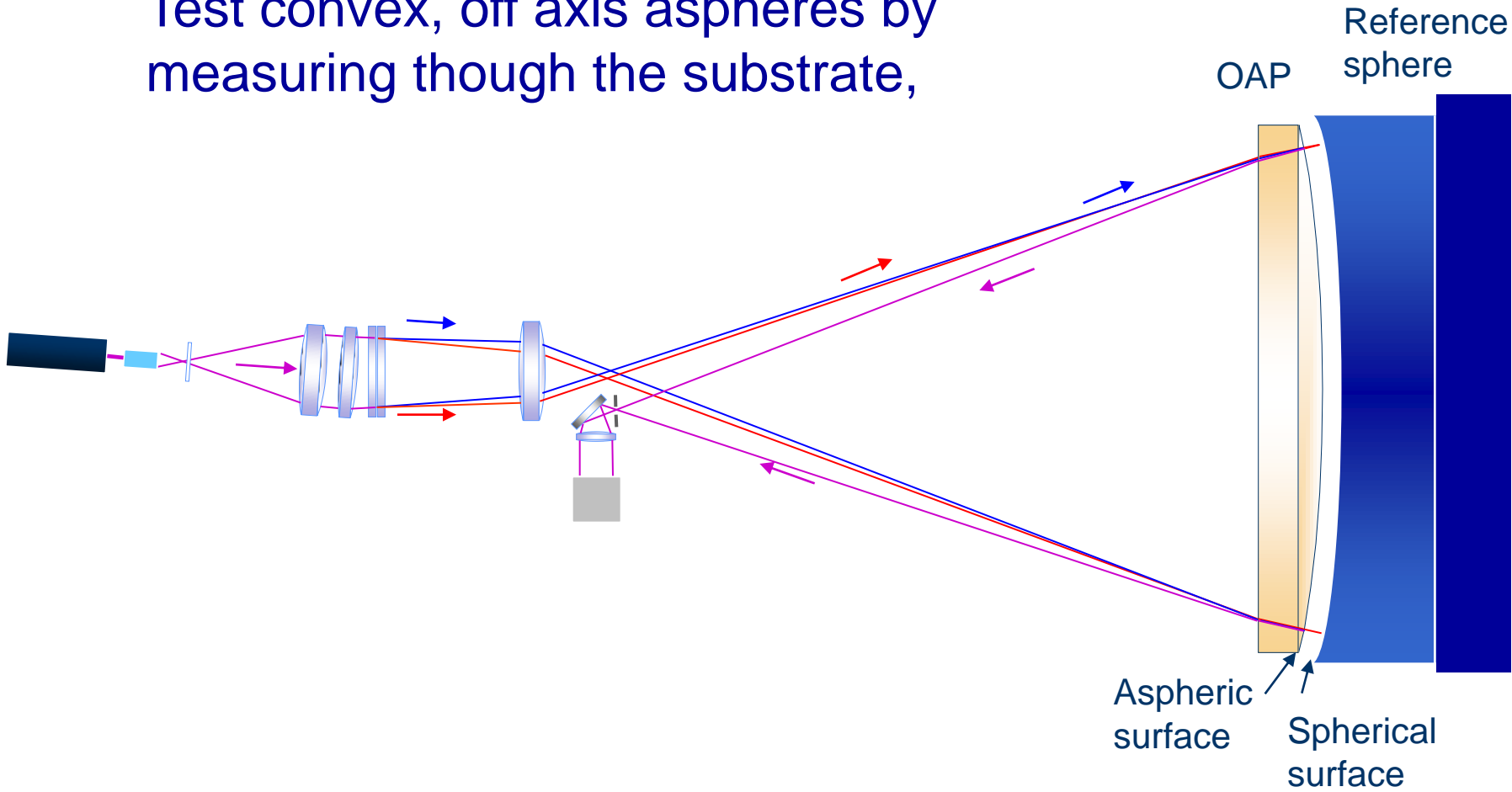
- Efficient fabrication of hundreds of mirror segments
- Complex support for each segment
- Active shape and position control for each segment

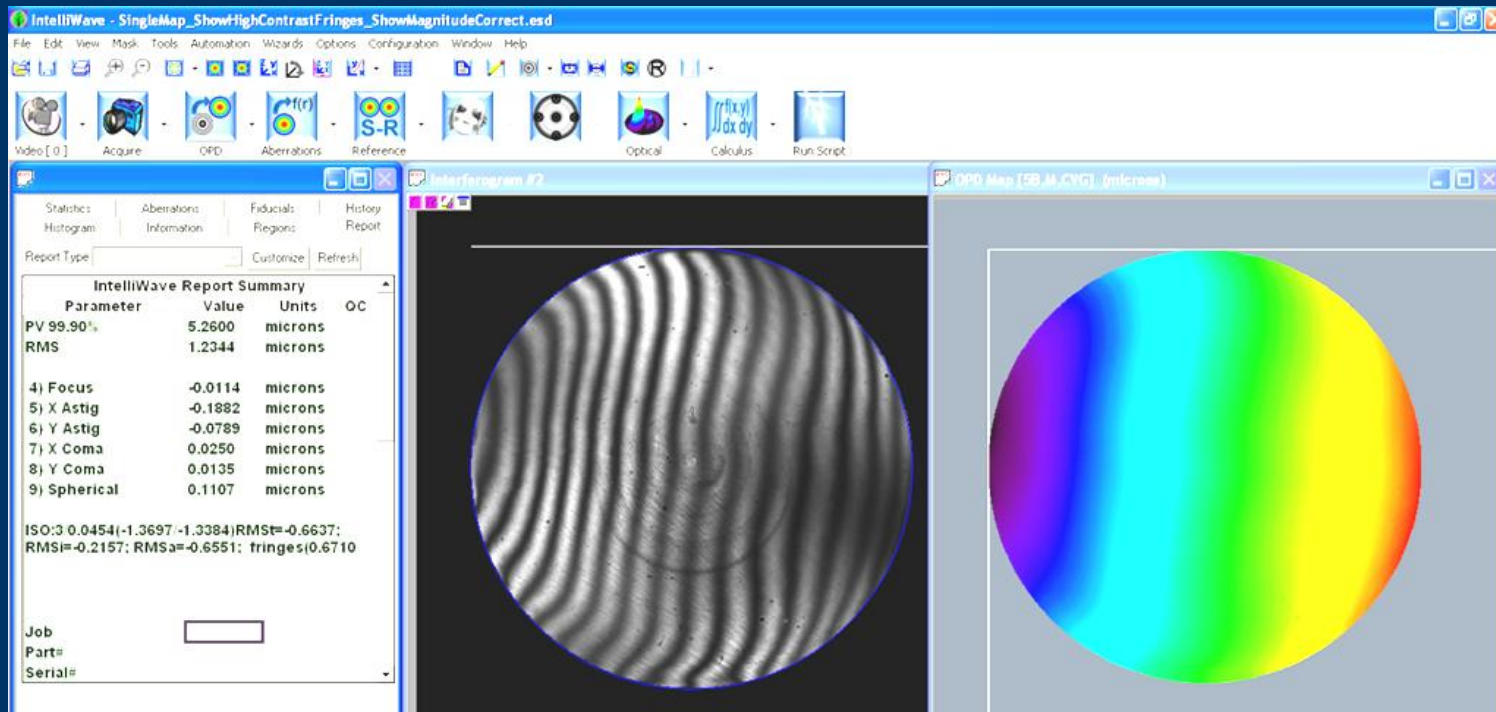
# CGH Fizeau test for primary mirror segments



- Common path – low noise
- Radius matching is easy, all segments compared with the same reference
- Detailed engineering analysis for TMT, E-ELT predicts 14 nm rms overall accuracy, 5 nm rms after some low order correction

Test convex, off axis aspheres by measuring through the substrate,





**Excellent fringe visibility**

**Excellent spatial resolution**

**Overall accuracy of < 4 nm rms**

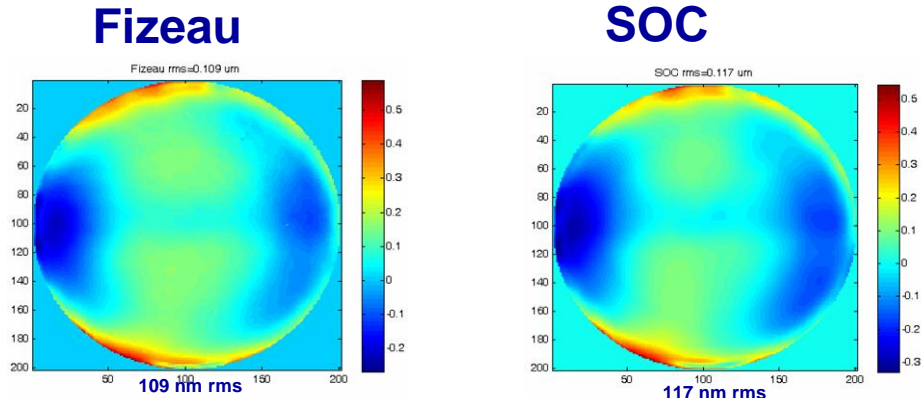
**< 1 nm rms noise per measurement (average of 50 maps)**

**Verified effects of striae in glass to cause < 1 nm rms**

**Largest sources of error: ghost reflection in CGH, coating irregularity on fold flat**

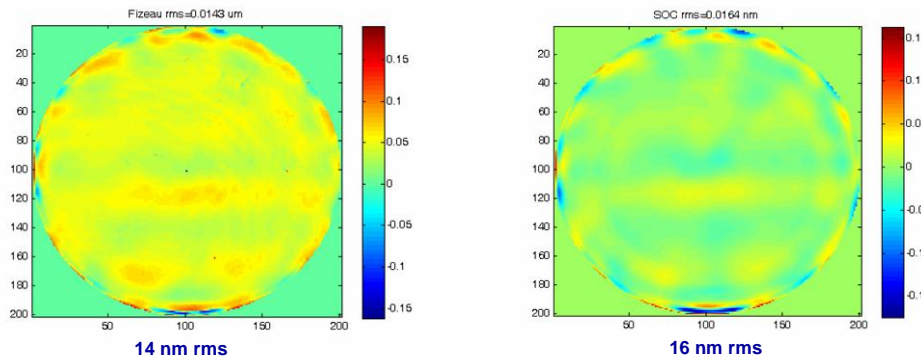
- The Fizeau test was budgeted as  $< 3.3$  nm rms uncertainty, after correction for low order terms.
- SOC measurements of the OAPs are consistent with this.

Raw data

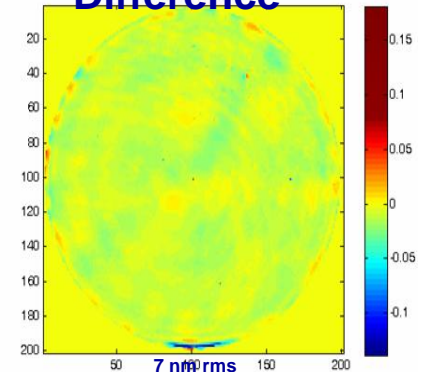


Astigmatism and coma from alignment were not needed to be controlled accurately

After removing low order terms



Difference



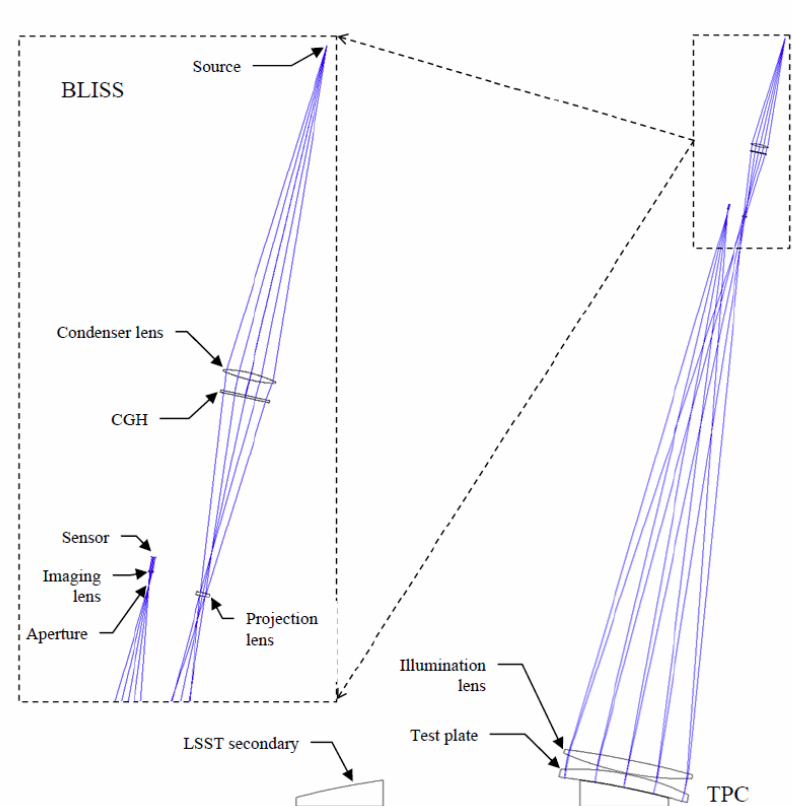
Largest errors in Fizeau came from  
coating defect on large fold flat 1 nm rms  
ghost fringes 1 nm rms



Combine several elements:

- Fizeau interferometry with spherical reference, corrected by CGH
- Vibration insensitive interferometry using polarization

Design for such a test for LSST was presented last summer. Prototype work is underway.



(M. Dubin)

- University of Arizona technology is enabling the Giant Magellan Telescope and the Large Synoptic Survey Telescope
- We are prepared to support TMT and E-ELT if those projects move forward.

